Final report

Strategic Positioning for Assistive Technologies

Project code: P.PSH1289

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Abstract

A global scan of existing and emerging assistive technologies was undertaken to understand the types of capability that are becoming accessible and could support the industry's strategic goals to increase the value created from every animal by 3-fold.

A design led approach was taken to understand the problems worth solving, in contrast to technology scans that often list tools and inventions but don't apply them to innovations that require a wide range of enabling capabilities to create real commercial value.

An overview of the functions, tasks and processes currently undertaken along the red-meat supply chain were then assessed and mapped to identify problem areas (opportunities) that could increase industry value. Value lenses included labour saving, staffing attraction and retention, improved alignment of supply chain outputs to consumer needs to increase value, and enhanced decision making to increase productivity and return on inputs.

Opportunity areas were then prioritised considering magnitude of impact along the supply chain. Factors impacting adoption were also considered in consultation with industry participants.

Project observations demonstrated that commercial engagement in research and development with a focus on extension (adoption) requires a clear vision at the outset. Bigger, bolder problem spaces that communicate a step change in capability and value are more likely to engage the right mix of participants for wider adoption. These bold solutions usually require integration of a broad range of technologies and enabling capabilities. A parallel project in partnership with MLA has also been undertaken to assess Assistive Technologies. This report heavily integrates the findings from that project (P.PSH.1290) in the recommendations of this study.

The development recommendations for Visioning and Sensing, in conjunction with Assistive technologies and other enabling capabilities outline three priority development programs covering:

- Extensive livestock production
- Intensive livestock production, and
- A stepwise evolution from assistive technologies to full automation for difficult boning tasks).

The processing stream considers MLA's current Y22 investment in lamb and beef automation and complements that program specifically. All three streams consider other programs of work in Objective measurement.

Executive summary

Background

MISP 2020 identified that the Australian red-meat industry needs to increase the value created from every animal by 3-fold to be sustainable. Furthermore, as one of the leading export countries, Australian processing cost were 24% higher than the United States, 75% more than Argentina and twice that of Brazil, all being major global competitors to Australian red-meat exports. Labour-related charges are the biggest area of disparity (Cost to Operate and Processing Cost Effectiveness reports “AMPC 2017-1062”). Research and development that clearly translates into commercial solutions to these challenges is paramount.

The Australian red-meat industry is the global leader in meat exports in terms of food safety, eating quality and product value. Considering we are a net exporter of beef, sheep, and goat meats and one of the largest meat exporters with greater than 70% of our production consumed overseas, the need to be globally competitive is paramount.

However, Australia has the highest cost of processing, predominately driven by high per unit labour costs and very high energy costs. Australia has a shortage of labour willing to do the jobs required in livestock production and meat processing and even with heavy reliance on imported labour, there is still a shortage of people required to fill essential roles. Our competitiveness as an industry depends on innovation in these areas.

(Cost to Operate and Processing Cost Effectiveness reports “AMPC 2017-1062”) indicate Australian processing cost were 24% higher than the United States, 75% more than Argentina and twice that of Brazil, all being major global competitors to Australian red-meat exports. Labour-related charges are the biggest area of disparity.

The Australian red-meat industry has been a global leader in research and development investment to enhance the effectiveness, competitiveness and sustainability of the industry supply chains while meeting consumer needs. Meat Standards Australia’s eating quality system and lamb processing automation are two examples of commercial successes.

Technology and ‘widgets’ are continuously being developed and refined to improve efficiency, worker longevity and safety, quality of products and ultimately business profitability. Technology adoption is not necessarily aligned with its potential benefits as it may not fit into current infrastructure available or the implications and benefits on the whole system may not be understood or well-articulated. A range of assistive technologies and visioning systems were reviewed for the beef and sheep supply chains from the perspective of research, application and adoption.

In the past five to ten years a range of technology has been deployed on farm and in processing plants. This has led to the collection of large quantities of data. The focus now needs to be on analysis data and creating information which informs decisions to optimises business processes.

The results of this research are presented to identify business processes and decisions – what’s not available now and what is required for this to be commercially available based on availability of existing products and their ability to provide accurate and reliable data. This report provides insight into areas where research, development and extension will assist the red meat industry to enhance continuous improvement and adoption of R & D initiatives.

Objectives

The project objectives which were addressed include to:

- Identify, assess, prioritise for commercial application
  - Relevant technologies from outside the industry
  - Potential service providers
- Determine solution desirability within industry
  - Readiness for value propositions from visioning-driven solutions
- Build a progressive adoption strategy for red meat companies throughout the project
- Define a business model, relevant to solution providers
- Determine the business case and approximate financial value to the industry
- Design pilot projects for implementation outside this project

This report describes the findings from the research undertaken and achieves these objectives.

Methodology

Desk top research was undertaken reviewing previous assistive and visioning technology projects in the red meat industry. A list of technologies currently available or deployable to the red meat industry was developed and each of the companies supporting the deployment and development of these technologies was reviewed. Interviews were conducted along the supply chain with large commercial companies to understand what technology has been trialled and or is in use and where the current gaps are in regards to commercially available and viable solutions. Analysis was undertaken from a whole of value chain perspective to prioritise areas requiring R,D & E which offer potentially the greatest gains from yield improvements and labour efficiency perspective.

Results/key findings

Suppliers of technology often focus on their widgets. Before deployment of widgets questions need to be asked:

- What decision or process is this supporting,
- Does it fit into culture, strategy and value proposition for the target markets
- If data is created from the widget, how and who is analysing the data in a timely manner to support the decision process.

From an R,D & E perspective questions include:

- Does the widget work in the existing system?
- If system changes are required, is this a completely new system or can it be adapted
- Does the widget offer opportunity, however exact deployment of where and how it will work needs further investigation (this is taken as needing 'development')
- Does the widget work but companies are unsure if they will invest? What is the reason behind the hesitancy?

Benefits to industry

The project has reviewed an extensive number of existing and application technologies from co-biotics to automation to robotics and identified key areas and technologies which have the ability to improve profitability and productivity for the entire red meat value chain in Australia. Labour availability and cost of labour is and will continue to be a major resource constraint. This report identifies pathways and areas to focus future R,D&E funds to maximise benefits.

Future research and recommendations

Bigger bolder innovation projects are required to seize the value opportunities industry is identifying. This requires implementation of RD&E in a way that enables bigger bolder inputs to create significantly greater return for the Australian red-meat industry. Avoiding a shotgun approach to R&D innovation is required and needs a very structured guidance to ensure transformational change. A more integrated approach to integrating visioning and assistive technologies in the following areas is recommended:

- Integration of OM technologies along the entire supply chain
- Integration of decisioning support for supply chain alignment
- Development and adoption of technologies to enable supply chain alignment
- Development and adoption of technologies that create productivity gains

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1. Background

1.1 Strategic considerations

MISP 2020 identified that the Australian red-meat industry needs to increase the value created from every animal by 3-fold to be sustainable. Furthermore, as one of the leading export countries, Australian processing cost were 24% higher than the United States, 75% more than Argentina and twice that of Brazil, all being major global competitors to Australian red-meat exports. Labour-related charges are the biggest area of disparity (Cost to Operate and Processing Cost Effectiveness reports “AMPC 2017-1062”). Research and development that clearly translates into commercial solutions to these challenges is paramount.

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The Australian red-meat industry has been a global leader in research and development investment to enhance the effectiveness, competitiveness and sustainability of the industry supply chains while meeting consumer needs. Meat Standards Australia’s eating quality system and lamb processing automation are two examples of commercial successes.

1.1 Emerging capability inventions

Technology and ‘widgets’ are continuously being developed and refined to improve efficiency, worker longevity and safety, quality of products and ultimately business profitability. Technology adoption is not necessarily aligned with its potential benefits as it may not fit into current infrastructure available or the implications and benefits on the whole system may not be understood or well-articulated. A range of assistive technologies and visioning systems were reviewed for the beef and sheep supply chains from the perspective of research, application and adoption.

In the past five to ten years a range of technology has been deployed on farm and in processing plants. This has led to the collection of large quantities of data. The focus now needs to be on analysis data and creating information which informs decisions to optimises business processes.

1.1 Converting inventions into industry innovation

The results of this research are presented to identify business processes and decisions – what's not available now and what is required for this to be commercially available based on availability of existing products and their ability to provide accurate and reliable data. This report provides insight into areas where research, development and extension will assist the red meat industry to enhance continuous improvement and adoption of R & D initiatives.

Learnings from commercial technology developments over the past few years has highlighted the importance of collaboration in problem solving and the impact that right company fit has on successful technology integration across multiple disciplines. For this reason non-technology drivers of capability and adoption has been included in the assessment matrix.

1.1.1 Assistive Technologies Introduction

Complexity requires human intervention

Compared to pork, lamb or chicken, the beef industry stands to gain the most from 'cobotic' technology. The human factor is integral to the processing of beef. Larger primal cuts are removed by knife from the skeleton and each other, rather than straight saw cuts through meat and bone. This involves dynamic adaptation of knife to cutting line on a cut by cut basis. This requires more complex vision and sensing than is currently possible to fully automate. So full automation of these tasks is still at least 10 – 20 years away.

The industry trend is toward more detailed sub primal breakdown, increasing the complexity of visioning. One processor stated that carcase breakdown has moved from 25 to +100 knife cuts per carcase over the last 30 years (personal communication reference from NCMC). So the need for these dynamic manual assist skills will at least remain the same if not increase over time.

Benefits of cobotics over automation

Changing market conditions and consumer demands are a consequence of the world we now live in. Global market perceptions, demands and agility to respond in the face of increased worker expectations impact on a business's competitiveness. The cobotics approach is more flexible to respond than the automated approach where fewer cuts are done more accurately at higher speeds. A number of other considerations should be taken into account including the following:

- Cobotics would provide the plant with an increased labour pool by including workers who may have knife skills but less physical strength.
- Younger generations are likely to engage quickly with the technology and see it as a positive work experience in what has not been an attractive environment for them.
- The capability of the technology to work with human intuitive movement means that it can adapt to change as quickly as the operator can.
- If further developed as a technology platform (per the commercialiser's original objectives), the device would have a number of end effectors with only limited reengineering and retraining of

staff before it is able to be effective and productive. This has advantages over multiple unrelated cobotics solutions in terms of maintenance, parts, R&D extension on base technology.

- The larger and more automated technology systems come at a much greater capital cost and can require more floor space than cobotics that impact less on existing processes.
- Fully automated systems have a greater business impact with any system failure. Workers using Hook Assist could simply continue with manual operations if a breakdown occurred.
- Boning skills are highly valued by operators and the Hook Assist allows these skills to be amplified as a benefit to the plant rather than removed and replaced by a tool which at present, don't have the visioning and sensing capability to replace some of the harder manual jobs.
- Small and large company needs: Large capital projects will not be suitable for all plants due to space, capital budget and other constraints.

Comparison has also been made in Table 10 between fully automated and operator assisted development pathways and differences between beef and lamb that will pose different automation challenges for beef.

2. Objectives

The projects objectives were to:

- Identify, assess, prioritise for commercial application
    - Relevant technologies from outside the industry
    - Potential service providers
- Determine solution desirability within industry
    - Readiness for value propositions from visioning-driven solutions
- Build a progressive adoption strategy for red meat companies throughout the project
- Define a business model, relevant to solution providers
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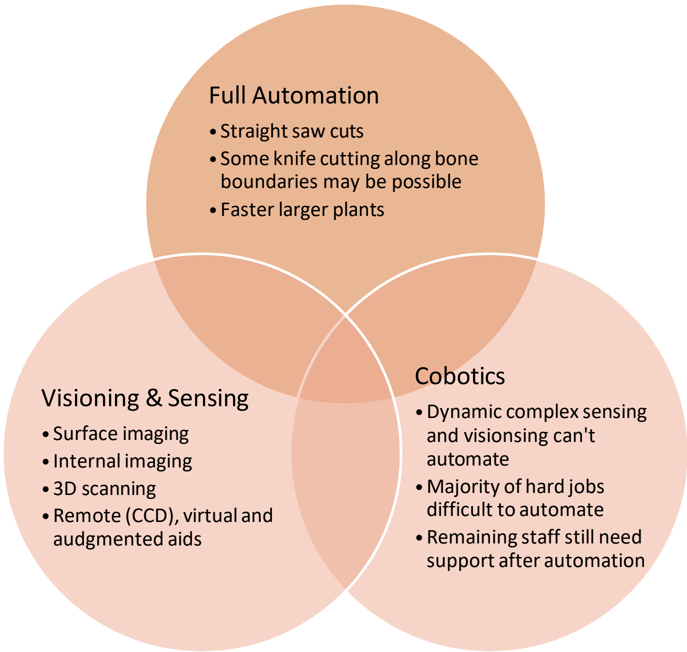
To prepare the final report relevant technologies and potential service providers from an entire value chain perspective were reviewed to understand application and use of technology needs to consider company and supply chain strategy, company culture, resource constraints including existing infrastructure and labour.

All of the objectives were achieved with the results, findings and recommendations provided in this report and associated annexes. Travel restrictions due to COVID were a barrier to engaging some companies and meeting to unpack detailed solution findings. The approach was adjusted from the original technology led focus to a problem-solving methodology. This inadvertently reduced the need for company specific engagement and provided a more robust set of future development recommendations as a result.

3. Methodology

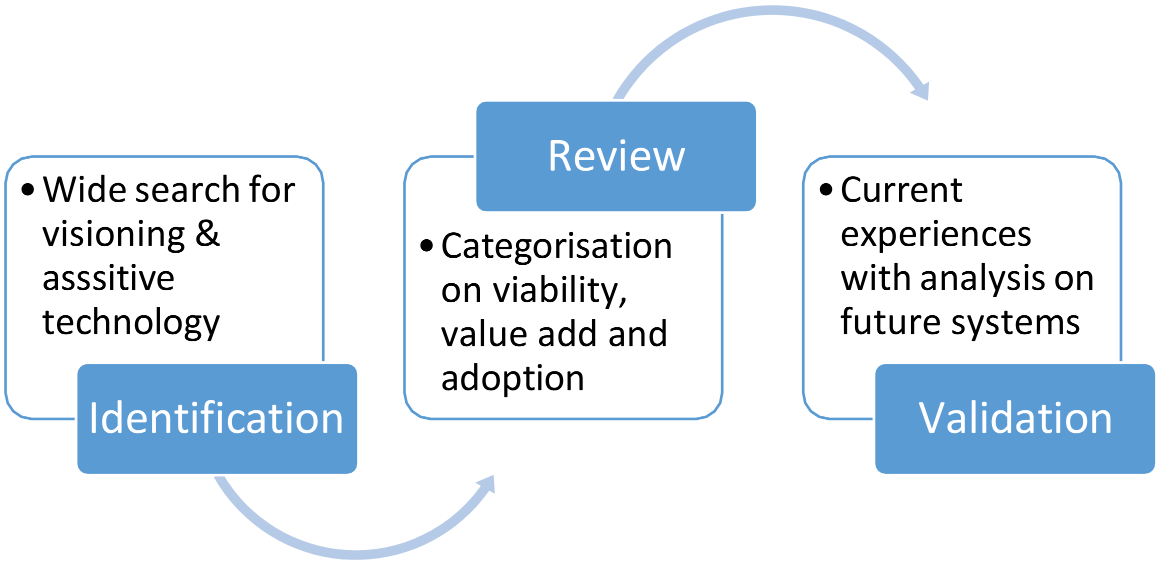
3.1 Integrated technology approach

Industry solutions require the integration of technologies for most commercial solutions.



3.2Overarching Methodology

The researchers started with an extensive search of the technology available in assistive technologies and visioning systems. The next step was to review the literature on research, development and application of the technology available. Technologies (widgets) were then categorised based on their commercial viability, likelihood of value creation and willingness to be adopted in the red meat industry. Interviews were conducted with industry and project staff working in beef and lamb automation and large commercial on farm operators on their experiences with technology.



The researchers started with the technology (widget) and reviewed the widget identifying what will add value. When conducting the final analysis to identify findings and recommendations the focus switched from the widget itself to the purpose, issue or decision the widget was addressing. Consideration was given to how the widget fits into the value chain, integrates with other technology and addresses future challenges, resource constraints and opportunities with value based pricing and marketing.

3.3 Identification

3.3.1 Identification of technology

The list of technologies was built through several sources:

- Desktop research: initially focusing on current state industry operations, then expanding focus to research leading technology across all industries for both visioning/imaging & robotics/assistive
- Previous MLA project work (providing an indication of technology types out there based on R&D into current technology)
- Leverage of existing Greenleaf work around technology applications and their relevancy to industry jobs

- Identification of the technologies that could potentially contribute to solving each job (either in full or as part of a broader multi-technology solution) based on interviews with industry experts.

Refer to Appendix A for the list of technology identified along with firms' details.

The list of companies was compiled in several phases:

- Phase 1: research into leading edge solutions that fall under 'visioning/imaging' or 'robotics/assistive'

- Phase 2: specific research into companies that would address individual jobs, i.e. single-purpose automation systems that could be developed into a fit-for-purpose solution for the single job

The list of companies in the Solution Providers Model is not a comprehensive list of all companies operating in the visioning/imaging and robotics/assistive technology industry, however, it is a list compiled with the intent of evaluating each individual technology category, the capabilities within each category and representing this with a set of companies of varying size and maturity. Where a technology category was under-represented, further research was carried out to identify companies that could fill the void.

3.3.2 Identification of Jobs

At its core, the industry has a set of discrete processes for example a tag scan in the production sector aims to build traceability, a certain knife cut produces an outcome. In undertaking this research the focus was questioning what is the optimal method for RFiD traceability, scribing and cutting, which result in an end product that meets product specifications and results in a high value product.

To communicate the industry vision for a process to prospective partners, they need to be equipped with the detail of what the industry process entails. With that in view, the research team aimed to develop process breakdowns with associated questions to focus partners on the automation direction for that process. A list of On-farm, Feedlot and Processing / Abattoir jobs can be found in Appendix B.

The list of jobs was built through several sources:

- Previous project work which Greenleaf Enterprises has identified key pain points in the industries that could be solved through the development of commercially viable technology applications.
- Internal workshopping with stakeholders- conducting high-level process mapping of industry operations & breaking the operation into individual components/jobs
- Industry case studies that have sought to illustrate what a fully optimised operation looks like for on-farm, feedlot & processing operations.

3.3.3 Review of Solution Providers

- The review of solution providers consists of a list of companies and a list of criteria to assess the feasibility of the companies for prospective partnership with the red meat industry.
- Further validation of company viability occurred through direct contact with companies of interest (based on the initial criteria & value proposition assessment) to gauge their interest level in developing solutions in collaboration with red meat industry stakeholders.
- The list of criteria used to determine viability of each company was subject to repeated revision and fine-tuning. Several criteria were initially used that did not yield additional value for example:
  - Quick to innovate and develop solutions- while a useful criterion in theory, it is not feasible to determine this consistently through desktop research due to the lack of publicly available data on this matter. This can only be accurately uncovered through

direct contact with companies- asking questions around their delivery history, standard project timeframes for technology updates of different sizes etc.
    - ‘Leaders in innovation’ status- due to the nature of the research, most companies were found to be leading innovators, based on independent reviews e.g. Fast Company ‘Most Innovative Company’ status, industry innovation awards, patent portfolios and ‘breakthrough technology advancements’ delivered).
- Therefore, the criteria scoring transitioned from being the ‘single source of truth’ regarding company viability to a contributing input into the overall value proposition of each company.

3.4Review

3.4.1 Technology Adoption

Historically, industry research and development of technologies with potential to add value has taken a technology focused lens. Success in technology delivering results is definitely underpinned by technology capability and application. However, commercial adoption of that technology involves many other aspects which are often overlooked. This indicates to some degree why commercialisation (commercial adoption) of technologies in the meat industry has room for improvement.

The traditional approach has seen innovation as:

- Observe a new technology outside industry
- Testing the technology [ZZZZ] (assuming a technology provider, [YYYY] provides it) to see if it can perform
- Asking ‘Can we *now* apply this to [XXXX] process?’
- Assuming “Yes” to the above, “We’d like a *solution* output”.

Although this is an important component of success, and what we will refer to in this methodology as “Feasibility”, this research focused on solutions that were likely to be adopted considering other required factors in conjunction with assessing the technologies themselves. The methodology utilised addressed the desirability, feasibility and viability.

1. Determine *desirability*
    a. ‘How keen is industry to see [XXXX] process revamped/replaced/integrated?’
    b. What is the value proposition for each solution? For example, do people desire this solution and how much do they desire it, relative to other solutions?
2. Determine *feasibility*
    a. ‘Is there a combination of technologies (of which [ZZZZ] is only one; e.g. CT-Scan + Robotic Arm = 2 technologies) which can address [XXXX]?’, noting this is not about a technology, but the integration of technologies ito create a commercial solution.
    b. What impact does this solution have on other processes?
3. Determine *viability*
    a. ‘Is there a provider ([YYYY]$_1$ or [YYYY]$_2$) who, irrespective of present capability, is willing to go the distance in commercialising this solution (not just the core

technology), and developing, or integrating other providers capabilities as necessary?

b. Is the provider (s) willing to push and pull with MLA and industry recipients (producers and processors) over re-configuration of deliverable specifications required for a commercially viable solution?

c. Is there a processor/producer who is willing to act as a test-site to support development?

d. Can the solution be delivered in a way that incentivises the provider to develop, invest and support appropriately, and in line with a businesses expected return on investment?

The idea is that a provider $[YYYY]_1$ is not special and can be replaced by a sufficiently eager competitor $[YYYY]_2$ who is willing to develop their expertise and business model to support the solution. Further, if the client is willing to provide enough direction, instruction and correction, the growing pains of such an evolving venture will result in a successful product, fit-for-purpose.

Such a product will directly solve the issue presented in the *desirability* phase, streamlining adoption to traditionally conservative processors and producers.

3.4.2 Assessment Tools

The way in which technologies now need to be assessed to consider the aspects of desirability, feasibility and viability requires integration of a wider range of factors. These factors all interact and impact in varying ways on the best approaches to progress after this project. A number of assessment methods were designed to support identification and capture of new value, and decision-making in this project. A tool utilised to support decision making when designing and apply research and development is the Figure 8 test, learn, reapply process as described in Figure 3.

Design & Test Process

The Design and Test process is an iterative design-led development process, summarised in Figure 3 and often referred to as a "Figure 8 of test, learn, reapply". This model enables R&D projects to acknowledge unknowns while moving forward by holding the project in a rigorous, manoeuvrable test and learn process allowing the program to adapt and pivot as required. Although this method is used in much longer projects it can be equally adapted to short projects and design sprints and will generally guide this project.

A targeted set of outcomes must be agreed upon for the Design, Test and Learn (and if required, Pivot) process to be effective. They enable the project team to remain focused on project outcomes whilst remaining flexible in design. This flexibility is necessary to achieve commercial deliverables fit-for-purpose, not fit-for-design. Figure 4 shows the result of applying design and test to a program Greenleaf manages. The 13 streams of work focused on delivering evidence and insights for pathway selection in Figure 4 aligned with business success.

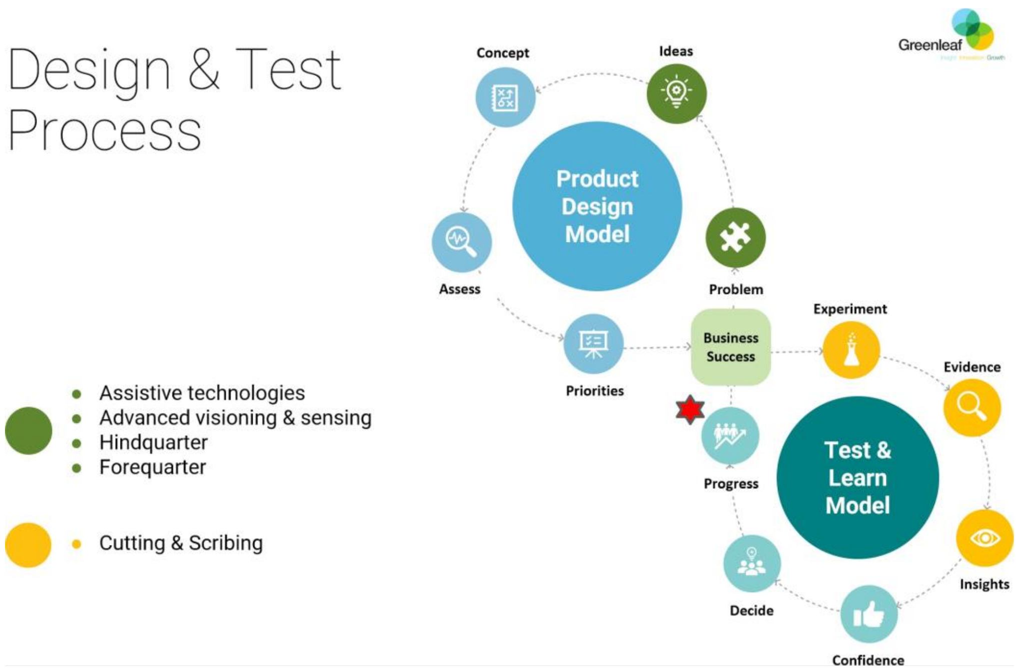


Figure 3: Design & Test process

Other assessment tools were used and descriptions are required Value Chain Applications Model findings with the Solution Providers Model findings in Shortlisted options section heading.

3.5Validation

The data collected for quantifying the value propositions for robotics, co-biotics and automation of beef and lamb cutting, boning and scribing in this project has been collected through site visits and using previously completed projects on value proposition in the industry for each processing theme. The references used are shown in Table 1. These references were mainly used to populate the yield benefits for specific cutting lines. In addition to these references two site visits were undertaken, at a beef and sheep/lamb processing facility. The labour requirements for these plants were collected for all the processing themes included in the model.

Table 1: Review of cost benefit reports used to support value proposition development

Report title	Reference
P.PSH.0888 - Lamb and Beef X-Ray Data Extended OCM Benefits and Transportability for Cutting Beef	(Brickell, et al., 2018)
P.PIP.0443 - RFID Traceability of Lamb Carcase from Slaughter to Boning	(Bryan, et al., 2015)
Cost Benefit Analysis for Combined Splitting and Spinal Cord Removal	(Fanning & Green, 2017)
A.CIS.0034 - Ex-ante scoping options for LEAP V	(Green & Bryan, 2014)
P.PIP.0327 - LEAP IV lamb middle cutting, Ex-Post Review	(Green & Bryan, 2014)

P.PSH.0629 - Lamb middle cutting system, Ex-Post Review	(Green & Bryan, 2015)
PSH.0579 - Ovine Robotic Kidney Fat Removal System	(Green, 2013)
P.PIP.0387 - Ex-Ante CBA for Automated Goat Cutting,	(Green, 2013)
P.PSH.0579 - (Milestone 5) - Ovine Robotic Brisket Cutter, Ex-post Review	(Green, 2013)
P.PSH.0579 - Ovine Robotic Dual Sani Vac, Ex-post Review	(Green, 2014)
P.PIP.0320 - Commercial Evaluation and Viability of Lamb Water Frenching	(Green, et al., 2013)
A.TEC.0093 - Picking, Packing and Materials Handling Review	(Green, et al., 2013)
LEAP III Ovine X-ray Primal Cutting System	(Green, et al., 2013)
P.PIP.0327 - LEAP III Ovine X-ray Primal Cutting System	(Green, et al., 2015)
A.PIA.0124 - Cost Benefit analysis of customised manual assist equipment installed in two plants for aitch bone removal and knuckle pulling	(Greenleaf Enterprises, 2009)
P.PSH.0335 - Beef Aitchbone and Knuckle Puller	(Greenleaf Enterprises, 2009)
P.PSH.0557 - The potential value of individual carcase identification and automated chiller sortation for an Australian lamb processor	(Greenleaf Enterprises, 2010)
Beef Loin Deboning Manual Saw Semi-Automation	(Greenleaf Enterprises, 2012)
P.PSH.0361 - Chine machine	(Khodabandehloo, 2011)
A.SCT.0047 - 2D, 3D & CT x-ray based scanning for measuring meat parameters	(Meat and Livestock Australia, 2019)
P.PIP.0470 - Beef Trim Management & Blending System,	(Nicolaou, 2018)
V.TEC.1704 - DEXA System estimations for red meat industry	(Shirazi, et al., 2019)

3.5.1 Shortlisted Options

- The business model matrix combines the Value Chain Applications Model findings with the Solution Providers Model findings, and then assesses the most viable industry solutions based on the overall value proposition and projected financial benefit to the industry.

- The matrix identifies the companies that can potentially solve each job (based on the technology capabilities each company has, and the technologies that can solve each job). It identifies the prospective financial return that solving each job will have for the industry; it also highlights opportunities to solve multiple jobs with a single developed solution, and the value that may be derived from that solution.
- Based on the above findings, the matrix informs the final recommendation regarding the highest value opportunities for the industry to further explore, and the companies the industry should first consider developing the solutions with to capitalise on these opportunities.

a handful of technology companies that could be potential partners to the Australian red-meat industry

Based on the review and analysis of technology and widgets combined with the value proposition, feasibility, desirability and validity a number were identified and then reviewed based on where they sit on the research, development and adoption spectrum. These results and findings are presented in the next section.

- The review considers issues, gaps, risks, solutions and recommendations that are applicable to a range of plant size, throughput, speeds of operation, configuration and products. Processors in each of the following categories were consulted within the project, as well as site visits to five processors wihtin these categories:

Plant	Plant Type	Species	Notes
1.	Medium Volume	Beef /Lamb	Mixed species
2.	Medium Volume	Beef	High number of product skus
3.	Medium Volume	Beef	Relatively low number of product skus
4.	High Volume	Beef	
5.	High Volume	Lamb/Goat	

- High level business case analyses was conducted on priority areas identified from the processor site visits and in conjunction with solution providers.

Summary of findings and key strategic considerations for opportunity areas that require visionig, sensing or assitive technoloiges which in many cases require integration of these and other technology capabilities.

4. Results

4.1 Key findings

Provide detailed information on all key findings/results that were identified during the project. Include all intellectual property materials as defined in the Agreement. This includes, but is not limited to; statistical analysis, tables, graphs, figures etc. generated throughout the project.

1. Problems to solve in priority
    a. Labour
    b. Cost competitiveness globally
    c. Extraction of supply chain value
        i. Possibly use the findings from the original CT and OCM work – 4 plants
    d. Other?
2. Show above and below in a diagram where coming from both ends and circular meeting in the middle with direction to go forward

4.1.1 Key problem spaces

Most of the tasks and steps in the supply chain were mapped out during the project with the objective of understanding problem areas, prioritising the value that could be created by solving them in isolation and as part of enabling wider value chain benefits, then understanding what types of capability would be required within potential solutions. The prioritised summary of these findings in Table focuses on problems that have the greatest opportunity for value. A number of other options will be easier to implement but are less likely to be adopted and have a lower impact on supply chain value over the longer term. These findings are considered in conjunction with key success factors in the next section.

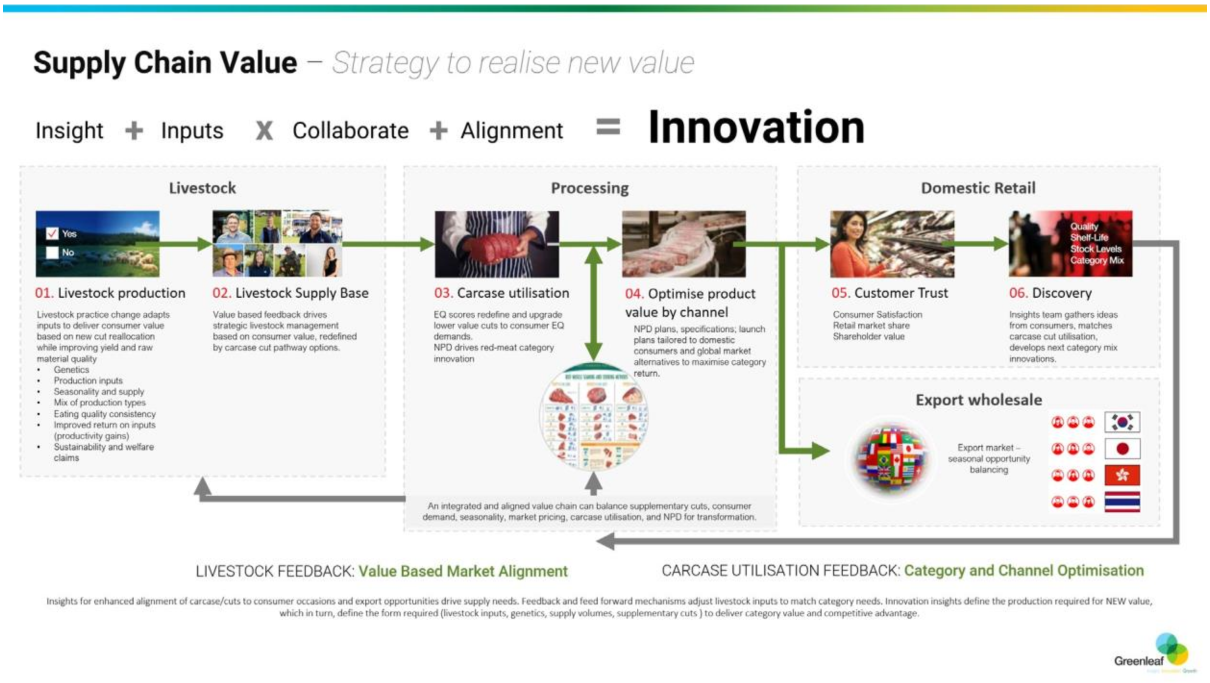


Figure 1: Defining each problem space as part of the interconnected supply chain

4.1.2 Key success factors

This project had a very clear focus on review of technologies and technology readiness at the outset. The purpose was very clearly to aid in solving industry challenges with the help of new and emerging technologies. However, the project very quickly broadened to consider the translation of technology capability into value and factors like commercial adoption, competitive advantage for adopters, commercial readiness, adopter confidence and engagement to name a few factors, all began to impact heavily on likelihood of properly addressing challenges. Observations were made around previous successes and failures, effectiveness of technology transfer, proportion of innovation driven by technology relative to other success factors. This section summarises some factors beyond the technologies themselves that are critical to developing a development roadmap.

Assistive technologies

Assistive technology R&D success has occurred where stress on manual operators is significant, and the task is simple enough to execute without hindering the persons efforts. Hydraulic pulling and lifting devices like the Proman and RTL pullers are examples of this. But they are close to the tipping point of user engagement. They hinder the operator’s free physical movement but relieve physical stress just enough for operators to accept the physical restriction imposed by the technology.

These types of developments have limited long term application across industry. More advanced technologies are required to support people where full automation is a long way off.

Major adoption requires gains to significantly outweigh new limitations – This is an obvious statement but often overlooked. Complimentary technologies that enhance the operators’ capabilities to perform the tasks more than the introduced limitations are required to develop commercial solutions with cobotic surgeries in human medicine is a good example of this. Solutions are becoming mainstream with advancements because the loss in the surgeon’s manual dexterity is compensated for by delivering far greater visibility of the anatomy being operated on through enhanced visioning and sensing systems.

Integrating multiple technologies are required for success – Cobotic surgeries are a good example of this, where the combination of assistive technologies and visioning systems, combined by a technology integrator, has enabled the addressing of more complex manual processes.

Technology specialists or Integration solution providers

Companies with technology specialities are usually not able to, or don’t want to broaden their narrow focus to develop a commercial solution. This is often because of business strategy or capability constraints.

Integrators that can pull multiple skills together into a solution are more likely to create value and provide commercial industry solutions than specialist providers. The recent work in MLA’s beef automation program with Rapiscan visioning provider, and Scott Technologies as an integrator is an example of this. Companies like Marel and Scott Technologies combine visioning, sensing, mechatronics, and assistive technology engineering to deliver these solutions. Scott Technology, originally a whitegoods manufacturing Automator, has had to become an expert in x-ray technology, waterproofing harsh environments, visioning and complex image analysis.

Many of the industries R&D projects have had a focus on visioning for collection of data for better decisions. However, this only addresses 1 of the priority problem areas referred to above.

Solution adoption requires other enablers

Observations throughout the project have highlighted the importance of factors outside the technology capabilities that can limit adoption. The broad developmet roadmap recommended in section 6 considers these barriers to adoption. By way of example, there is a very low adoption of proven technologies and R&D in northern Australia.

- On-farm challenges around adoption and return on investment point more to cultural barriers to adoption of core R&D – readiness for adoption is a limiting factor and requires activities to support the change management processes.
  - Where technology can demonstrate value and can be presented as part of a wider company initiative, there is likely to be more support for development and adoption.
  - More effort is required to get engagement, but the adoption issues faced with siloed implementation are likely to be addressed as part of the broader implementation.

Enablers of adoption

A range of additional factors beyond the technologies themselves contribute to adoption barriers and to the defining of the problem space.

1. Company strategy and vision alignment with benefits from technology applications

Research and development is more likely to be supported and technology is more likely to be adopted when the benefits of the technology align with the firms strategy and vision.

> Company A identified a diminishing labour resource as a constraint. The company strategy focused on optimising the business through improving technology, equipment and processes to make tasks easier and more enjoyable. Staff were asked what jobs they didn't enjoy doing and what areas could be streamlined to reduce manual handling. The company purchased equipment which wrapped pallets, stacked boxes, made boxes and labelled boxes.

On the flip side – a company invested in some technologies but did not have a solid company wide approach. The tech was considered the solution but was not supported by an integrated strategy – value was not created.

Another company installed robotic equipment but did not have the technical skills to support and the performance was worse than manual.

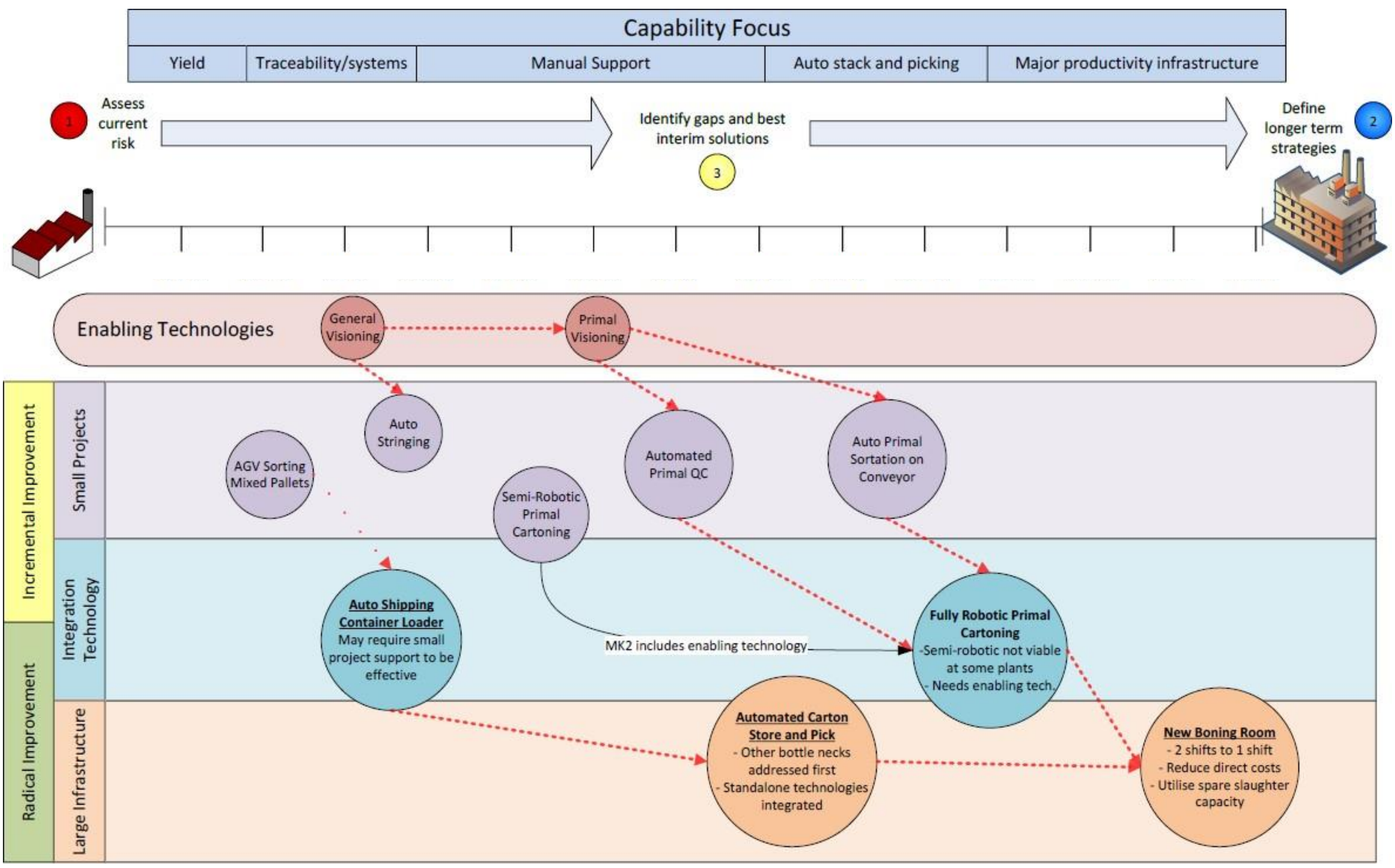


Figure 2: Progressive development of capability adoption as enablers to next stage innovation

2. Value proposition is well understood

With adoption, requires change management, time and cost. For some technologies the value proposition (cost verses benefits / increase uplift) is not well understood, articulated or isn't available and therefore the technology isn't adopted. Providers of technology, researchers and industry should ensure that transparent business case studies are provided to enable firms to understand the costs, inputs, staff capabilities required and the potential benefits of adoption.

Confidence in value proposition and the pathways for development. Combines a number of aspects required for delivery and connects them to the end vision and value. – example in the Teys Project and in others AMPC projects like Kinea as a collaborative. Everyone wants to be aware of in case there is something they could miss out on , but no one is making a commitment.

3. Product is fit for purpose

In the case of on farm equipment there are examples where technology requires mobile phone reception, reliable power sources and Bluetooth connections. In many places there is limited to no mobile phone reception, no to intermittent power and Bluetooth struggles to connect due metal yards/crush and environmental factors (dust, etc). In the case of processor equipment there is an example of suit which supports the breakdown of a carcase which was trialled however the circuitry was not built in a way which was water proof, so could not be easily washed down at the end of every shift. This is about managing expectation about the R&D cycle and how projects are funded. Indsutry based projects, driven by solution providers, without proper engagement from indstury commercialisers who understand and are committed, not just to the journey but the commercialisation process, are important.

4. Learnings from the Kinea Design System

'Cobotics' or Intelligent Assist Devices (IADs) provide a potential solution to some of the inherent challenges of manual meat processing tasks. Its primary capability is the support and amplification of the human sensory capacity, intuitive to the skilled operators in the boning room. Application of this technology to support operators in physically challenging tasks like aitchbone removal in Figure 2 could improve operator longevity in the job and quality of life.

IADs take advantage of progress in digital power and digital logic state-of-the-art sensor, actuator and controller technologies. These devices are improving human productivity by replacing traditional mechanical, pneumatic and electro-mechanical material handling devices, and by providing power-assistance to humans in industrial and non-industrial applications, that so far have not been addressable by traditional devices.

Figure 3: Hook Assist prototype technology

Figure 3 demonstrate the prototype system in action and various boning applications for the Hook Assist application.

HookAssist installed in 'spare' boning room at Brooklyn

HookAssist installed and being trial in a chiller at NCMC.

Figure 4: Hook Assist prototype system in industry trial sites

Table 2: Primary benefit areas for Hook Assist technology platform

Benefit	Description
Yield increases	Increased saleable meat yield results from reducing boner effort (and fatigue) allowing greater focus on knife work and precision. Aitchbone pulling enables additional yield benefits due to extra available pulling power, freeing the boner to focus on knife work.
Increased throughput	Improvement in rate of processing where multiple systems make the hardest jobs easier. (This is dependent on plant manning's and assumes hardest jobs are the limiting tasks).

OH&S	Reduced physical exertion will reduce fatigue and occurrence of musculo-skeletal and associated injuries. This will improve operator safety, and lengthen worker years.
Labour savings	Reduction in labour units required to complete heavy jobs in some plant configurations.
Reduction in staff training costs	Making these higher paying jobs easier will lengthen operator life, reduce turnover caused by fatigue and increase retention rate.

4.2On farm technologies - What the systems can't do

As part of the analysis, what currently exists was inverted to understand what research, development, adaptation and adoption is required, in essence this section highlights what the systems and technology are unable to do.

Individual animal management and recording liveweight

On farm technologies with regards to individual animal management based on the RFiD tag exist. In discussions with large operators, they have identified the current systems to manage the animals at an individual level has functionality issues. Larger operators have multiple properties and 20,000+ animals, which the systems are unable to manage the scale and provide information on individual animals in the yards without the systems freezing.

Hardware for example laptops, tablets and weighing scales are also not without their issues. Computers overheat in Northern Australian conditions, weigh scales and associated systems may not connect or may not take readings quickly as they are waiting for the animal to stand still to take an accurate reading. This maybe suitable when working a few hundred quiet stock through the yards in a day, however when processing thousands of animal who may have never had contact with humans or a set of yards before creates issues.

The yards and crush infrastructure impact the technology solution. For example steel yards will impact wireless connectivity. In some yards there are separate weighing scales before the crush and EID reader at the crush to record animal husbandry processes. It is nigh impossible to connect the devices by Bluetooth due to multiple items being present in a 5 metre radius.

System connectivity, data integration and whole of supply chain analysis

There is limited system connectivity and whole of supply chain when dealing with the larger herds. The animals shift between properties, with some applications keeping the data from the previous properties and adding to previous data while other applications are not set up to follow the animals across different properties. Different livestock and pasture management applications are at different levels of maturity, with some applications not having API access allowing data integration. Whole of supply chain analysis where animals are analysed using their DNA, average daily gains and carcase results is currently lacking.

Priority opportunity areas

The tasks and processes along the production chain are included in the appendix x. The highest value opportunities are summarised in the following Table x. Further to this projects research, IoT stuidies conducted by MLA in 2020 were also considered as part of a integrated solutions.

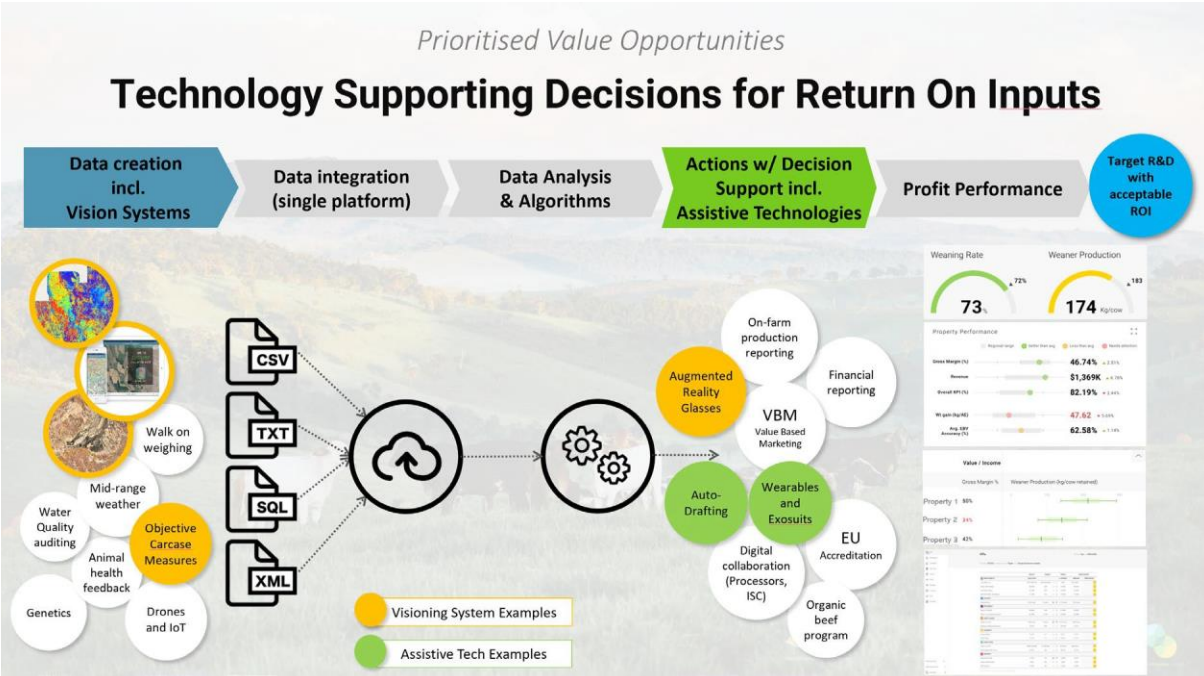


Figure 5: An integrated approach to visioning and sensing and applicable assistive technologies helps prioritise opportunity areas.

Include a summary of commentary on the table here broken into the following headings.
Key industry themes:

1. Value based transactions
2. Enhanced operational decision making to increase supply chain alignment to customer needs to improve return on inputs
3. Improved productivity through enhanced capability to address product cost
4. Increased value realised through enhanced capability to supply the highest paying customer for that product

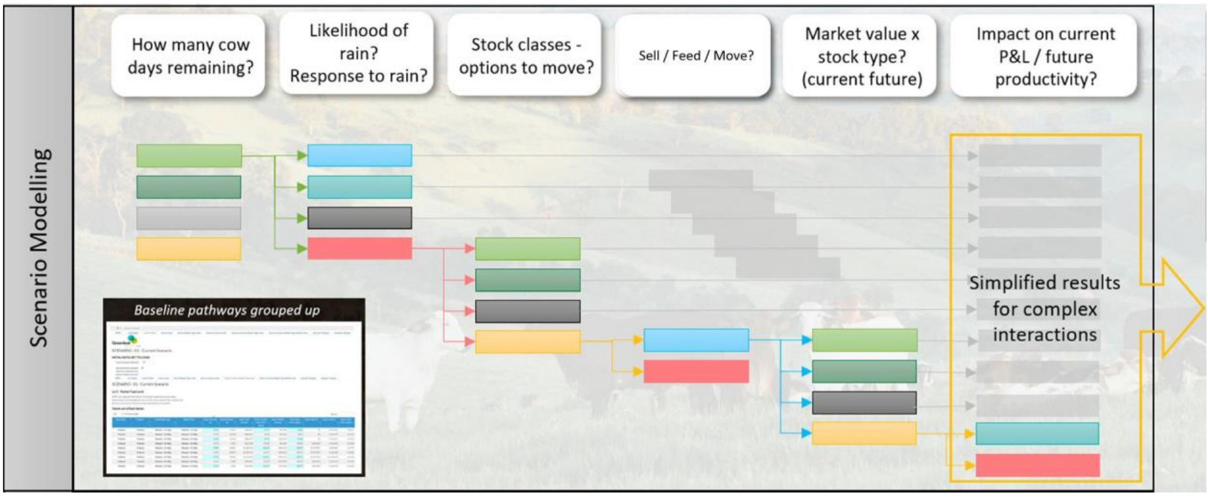


Figure 6: Decision processes impacting profitability that require information such as visioning data or assistive technology interventions to enact the resultant decisions

Visioning systems for OM measurement

Progressive development of capability

Adoption should be a core focus of these programs.

Many producers don't weigh livestock or if they do, use broad weight categories for drafting and decision making. A range of easier to measure systems like visioning for BCS can add value quickly. Whereas sophisticated visioning and measurement devices are unlikely to be adopted at this stage due to cost.

Pricing signals are also a barrier to adoption

Genetic tests are becoming more affordable and are likely to be more practical than visioning systems for a number of reasons:

- They provide information of a predictive nature about how an animal may perform into the future. This is potentially more valuable than point in time measures which could forecast future [make this into a table]
-

Visioning Systems for enhanced decision making

Table x summarises the key data capture points for decision making broken into categories:

- Production inputs
    - Pasture and Biomass production
    - Input capture
- Livestock measurement data
    - Weights
    - Condition socres
    - Growth rates
    - Genetics
    - Individual ID and traceability
    - Body composition
        - Ultrasound, 3D camera, NIR
- Livestock decision pathways
    - Drafting
    - Sales
    - Decision implications

Figure x – Decision Tree matrix – use Kidman proposal

Assistive Technologies

Assistive technologies in the on-farm space were not considered a major focus area of R&D investment at the current time for a number of reasons:

- Adoption rates will be slow and unlikely to generate a solid BCR
- Technologies tend to be less sophisticated, meaning they have less development need, or are readily available such as walk-over weighing and drafting systems.
- Drones have been included in previous work

- Labour shortages are an issue but internet connectivity and quality of life in remote areas are more likely to attract staff than tolls that help the actual tasks.
- Someone willing to invest in technology is more likely ot be strategic, with a focus on enhanced decision making.
- challenge with ROI and diverse single customised installs.

Wearables, water monitoring, drones etc all helpful but priority on Value Propositions????

Mustering, laneways and monitoring pens.

IoT devices Have not been considered directly in this report. Another program of work was completed in 2020 that identified opportunities for IoT systems. It has been mentioned given integration of visioning systems will require integration support from IoT devicies in many cases.

Enabling capabilities for Decision making

Consultation was undertaken with a number of properties including on-farm visits. Due to COVID the site visits were in Queensland and focused on beef enterprises. Existing technologies are readily available but there are a wider range of enabling capabilities required to get the best use from existing technologies. The extent to which these capabilities are developed will impact on ability to engage in development and commercial install of more advanced technologies.

Access to data –

Capturing data – is a challenge in remote locations and relates directly to visioning and IoT technologies.

Cleansing data –

Understanding the data –

Analysing data for insights – is the single goal when implementing visioning and decision support technologies. One set of challenges in increasing the management interventions in an extensive bioeconomic system is integration of all the related drivers and enablers, coupled with the right management controls. An adhoc, or piece-meal approach to enhanced decision support won't account for the interaction of all the parts (economic, biological, environmental, seasonal and cultural) and may disappoint.

Forecasting, predictive analytics, optimisation, AI, Machine learning are terms the production sector is becoming familiar with. However, generation of commercial value above status quo requires solid foundational capabilities to be developed.

Data Management and Integration

- Different levels of modernisation and sophistication – for example not all applications have API end points and accessibility.
- Specialised systems hard coded or securely coded which won't shared underlying source information with other systems without substantial development costs

Data governance and management - security

Data ownership – who owns the data – the person who collected the data or the firm which provides the software which collects the data or the firm which stores the data on the clients behalf.

Manage technology – people who don't have a background in technology (hardware and software) to manage technology in a sophisticated way. For example, when a system changes staff may not be able to do a range of tasks –

Barriers to adoption - of visioning systems include many of the above capabilities.

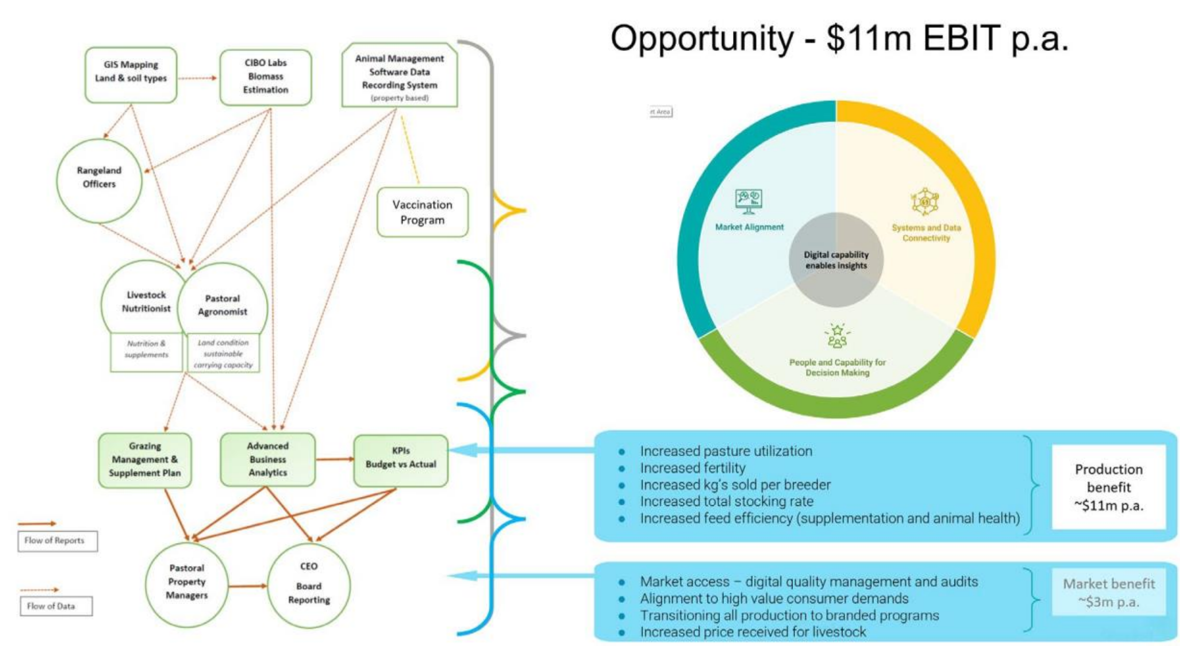


Figure 7: Example of integrated processes in a bioeconomic livestock system with associated value propositions

The degree to which a supply chain creates value is impacted by the capabilities developed that help leverage available resources for maximum value across the entire supply chain from production to end consumer. Part of this project included a preliminary assessment of the WA beef industry capabilities. Opportunities to support new capability were identified that could underpin new value.

The Figure 22 summarises the groups of capabilities that impact on realising value and the framework used to assess industry capability. Resource capabilities include tangible physical resources such as genetics, land assets, infrastructure and processing facilities. In addition less obvious, but in some ways more important capabilities (S.C. signals and connectedness) describe the way in which information and market signals are communicated along the supply chain. These information sharing and market signal activities help leverage physical capabilities to align with markets to realise value. The third tier in the figure describes the wider market forces in which the value chain operates. These include external competition such as other value chains (Eastern states beef, international competition, other protein sources) and political and regulatory forces such as market access, exchange rates and economic policy. Although this last section has an impact, it exerts the same force across all supply chains and as it is difficult to influence, does not have any focus in this study.

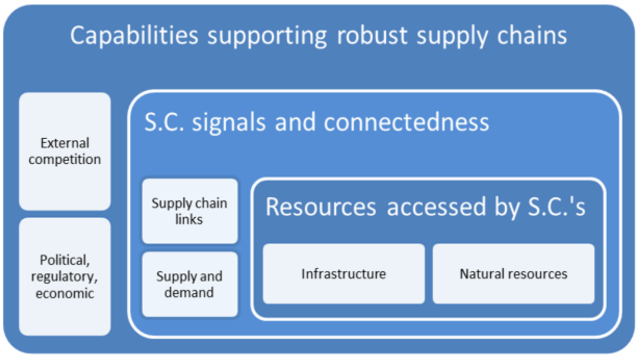


Figure 22: Capability groups used to assess value chain effectiveness

Well-developed capabilities help more accurately identify, align with, and access maximum market opportunity for the natural resources. These effectively minimise risk and increase confidence to invest in further capability development. A lack of capability along the value chain has two major impacts:

- Limits the ability to realise potential value
- Limits in severe cases (and in the case of WA Beef) the development of new capability due to high risk created by capability gaps. This lack of opportunity results

4.3 Beef and Sheep Processing

Priority opportunity areas

The tasks and processes along the production chain are included in the appendix x. The highest value opportunities are summarised in the following Table x. Further to this projects research, IoT studiies conducted by MLA in 2020 were also considered as part of a integrated solutions.

The report found that average cattle processing cost per head was 24pc higher in Australia than in the United States, 75pc higher than in Argentina and more than twice as much as in Brazil. AMPC's report found labour-related charges make up nearly 60pc of total operating costs in Australian facilities, compared with less than 50pc in the other countries examined.

- 130,000 jobs

Key value propositions were to improve efficiency and optimises yield and quality to increase profitability. The two primary areas of need include:

- Enhanced decision making
- Productivity gains focused on labour saving

On average, operating costs across Australia approximated $360.62 per head of throughput or $1.22 per kg HSCW.

On average, labour-related costs in Australia make up just over 58 percent of total operating costs, excluding livestock purchases. A significant proportion of labour-related costs in Australia are subject to either Federal or State government legislation, estimated to account for approximately 85 percent of total labour-related costs in the beef processing sector.

MLA has successfully developed lamb processing sensing and automation technologies in collaboration with commercialisers and industry partners. These technologies transform the cost basis for processing. Their increasing commercial robustness has fuelled in part industry awareness, acceptance, and now a confidence to invest in automation that is resulting in continued adoption.

Digital data collection and analysis from these automation systems are also providing objective measures for improved decision making along the entire chain and are beginning to enable whole of chain transformations.

Beef processing is more difficult to automate than lamb processing for many reasons. Although Beef DEXA scanning is driving some level of pre-boning room automation, the opportunities are yet to be explored properly. Given the significantly greater size, value and complexity of the Australian Beef Industry relative to Lamb, the opportunities and potential value from these investments is significant.

Stepping through the process chain there are a range of decisions, technology to help with these decisions and levels of technology application and capability

Visioning Systems for Objective Measure

Visioning for value based marketing is well advanced in terms of capability. Eight potential new objective measurement technologies are in the process, or close to being certified for commercial use in Australia. A number of other systems like NIR have been trialled over many years and recent collaboration between Australian and New Zealand companies is progressing towards a commercial prototype. Given the proliferation of new technologies it is unlikely the market is big enough to support all of them.

The focus of this project has been on the prioritisation of visioning technology developments. But the common theme throughout the research has been the integration of multiple technologies and or capabilities, and as parts of a larger vision for commercial value creation.

Talk about ViaScan and adoption – what are the other factors preventing adoption? Needs a broader integrated approach.

Enabling capabilities required to support OM visioning adoption

Data capture and analysis – is only the first step in commercial application of OM visioning systems. Many of the emerging vision grading systems are providing more accurate measures of existing attributes. Some are creating new measures like the lamb IMF reading. It is one thing to obtain more information about a carcase, but another to manage that to commercial value and over time, increased supply chain value. Some of these other enablers are included here.

Plant infrastructure – is required to manage the sortation, ordering and flow of product in new ways that are required to extract the additional value.
Grading and sortation of carcase into right grades and then into the right cut groupings to be managed through the boning and packaging rooms is then required to act on the results of OM visioning results.
Location of cameras in the processing facility is also critical.

Product breakdown decisions - need to be made through robust data analysis to optimise yield and value including allocating the right product to the right market.

Feedback - information from these systems is an important enabler of industry improvements. However, there most likely needs to be an increased processor confidence that they will be able to extract the new value they are measuring. The enabling capabilities above are a minimum in doing this.

Pricing Signals – will have a big impact on driving better alignment of production practices to market needs which equates to supply chain productivity. It is one thing to send feedback, but another thing to pay on new measures. There are two key risks to processors in changing payment methods:

- Incentivising some attributes while disincentivising others will change their supply base and possibly reduce volume supplied
- If premiums are paid, this will increase the supply of livestock with those attributes.

In both cases, if the processor is unable to monetise the full value of these livestock cost shifts, or reduces their volume, this represents a significant value loss.

Visioning for automation and cost saving

Give background on the beef automation program and the sheep automation programs. Summarise the breakdown of labour across a plant (job roles and show where the big opportunities are. Include the AMPC costing charts in here.

Pull in from Kinea AMPC report about labour

Efficiency – cobotics and automation to help reduce WHS issues, open up labour force and reduce labour required

Assistive technologies for labour saving

– considered in conjunction with visioning technologies

Top 5 opportunity areas for development

Plant process	Decision	Data & data source	Technical capability	Benefit (labour, yield>?)

1. Looked at processes
2. What each creates or doesn't create
3. Pulled out the themes
4. Drivers, capabilities, readiness – technologies
    a. Barriers & technology to adoption

1.1 Value Proposition Priorities

What are the issues and what can't we do now and what we don't do very well?

The Table 2 shows the grouped benefits for each area of processing facilities. For example, lamb boning in the table summarises a number of different boning technologies including but not limited to visioning and assistive technologies. The individual solutions are described and quantified in the detailed worksheets, then grouped up here to the 'Summary Results':

- This shows 'Total Opportunity' and 'Total RRP' for Beef, and Small stock applications.
    - The total opportunity is calculated using the total benefit for each processing theme. This is the maximum potential value increase that could occur.
    - The RRP includes a discounted benefit for each automation solutions where 80% of the full opportunity is realised, then integrated with a 24 months payback to calculate the upper RRP that could be afforded.
- The value of each sub-group is then totalled, summarising the full opportunity across all opportunity areas. Note that additional opportunity areas will be identified and expanded on throughout the project. Some technologies will be able to deliver a greater portion of the

full opportunity when commercialised, while others will deliver accuracy below the 80% once commercialised.

Each group of opportunity areas can be worked through with each processor for easy comparison of benefits.

Table 3: Opportunity analysis within the processing sector for Beef and Small stock

Summary Results

	Beef		Smalls	
Processing Themes	Annual Opportunity	Average RRP*	Annual Opportunity	Average RRP*
Slaughter (Bovine, Ovine, Caprine, All)	$4,488,965	$8,071,321	$4,235,328	$6,972,860
Boning - Beef	$7,478,391	$10,578,104	$0	$0
Boning - Lamb	$0	$0	$11,430,723	$15,063,084
Boning - Goat (& Mutton)	$0	$0	$413,683	$827,366
Carcase Chilling	$344,736	$689,472	$355,680	$711,360
Pick and Pack (and primal bagging)	$2,137,363	$4,274,726	$2,393,321	$4,786,643
Carton Handling	$1,654,733	$3,309,466	$1,747,655	$3,495,310
Product and Material Handling	$606,311	$1,212,622	$275,789	$551,578
Traceability & Integrity (A Boning Room focus)	$413,683	$827,366	$275,789	$551,578
Co-Product Processing	$418,163	$836,327	$896,314	$1,792,627
People Safety	$0	$0	$689,472	$1,378,944
Food Safety	$0	$0	$0	$0
Total Benefit	**$17,542,345**	**$29,799,404**	**$22,713,754**	**$36,131,350**
Per Head Benefit	**$104**		**$21**	

** Based on assumed % of benefit realised & modelled plant size & payback period*

Solution areas proposed:

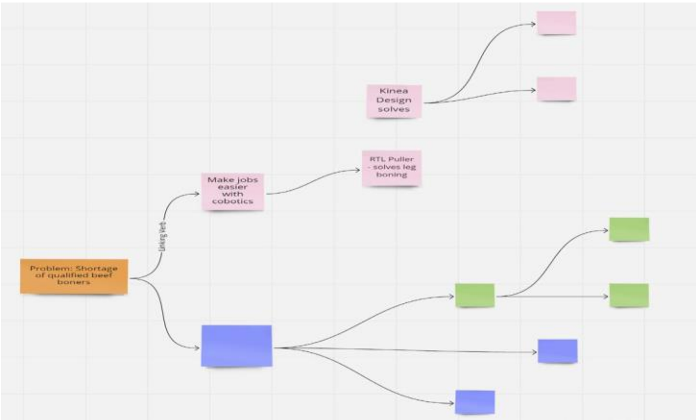
1. **Meat Processing Assistive Technologies** – compliment MLA's Beef Automation program (outside Scott Technologies field – less automation and more robotic)
    a. Wider adoption of MLA's beef automation system will cut across some traditional beef boning processes.
    b. Barriers to adoption will be the significant adaptation of existing boning infrastructure while still requiring existing labour to process the forequarter and hindquarter.
    c. Changes in boning room layout without improving forequarter and hindquarter boning may limit adoption of middle machine automation.
    d. MLA has undertaken some work in assistive technologies as early as 1994 and through until late 2015. Industry R&D and commercial pilots have had a mechanical focus with rudimentary devices that ineffectively carried some of the force in manual jobs.
    e. Advances in robotic surgery in human medicine researched during milestones 2-5 have occurred as integrated providers have adapted technology advances across multiple disciplines.
    f. Broader adoption barriers are already being considered in the MLA Beef Automation program and are beginning to be addressed as part of the next stages of R&D towards a commercial prototype.

Figure 8: Da Vinci Vision system integrates assistive technologies to enhance doctors capabilities

Across the many different assistive technologies, there are lots of emerging solutions that could help with specific jobs. But many of these are horizon 1 solutions, still require a lot fo investment to make them industry ready, and don't solve the longer term challenges.

Key Message about pathway - Below shows that some development paths are not going to end up with the best outcomes for industry. This level of strategic and planned R&D enables more specific selection of development pathways that have a greater chance of solving the core challenge.

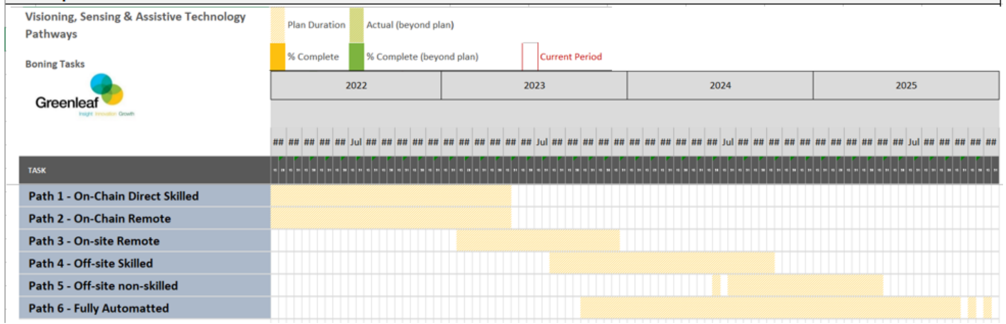
- This also provides a vision for commercial companies to engage in.
- A development path that enables test and learn towards a well defined commercial outcome also helps guide a dynamic development process.



Development Pathway Options – Meat Processing

Table 4: Development opportunities – Meat Processing

	Path 1	Path 2	Path 3	Path 4	Path 5	Path 6	Path 7
Problem Space							
Limited and reducing availability of skilled boners and at pay rates making Australia uncompetitive.							
Shortage of labour is preventing other tasks such as offal collection and value-adding enhancements							
Processor Pains							
Boners don't show up for work							
Only the strongest people can do the tasks, limiting available work pool							
Salaries are increasing to attract people but low skilled jobs in other industries are attracting these people and at much higher pay							
Females don't have the physical strnegth to do the jobs but have much better dexterity and attention to detail.							
Solutions	**Path 1**	**Path 2**	**Path 3**	**Path 4**	**Path 5**	**Path 6**	**Path 7**
Gains	On-Chain Direct Skilled	On-Chain Remote	On-site Remote	Off-site Skilled	Off-site non-skilled	Fully Automatted	
Labour pool available							
Female factory workers	1	1	1	1	1		
Extend working years for existing boners	1	1	1	1	1		
Part-time workers - school hours etc.				1	1		
Students - the new McDonalds (after school for a few hours before dinner)					1		
Off-shore lower pay rates					1		
No labour required						1	
Development timeline to commercialisation							

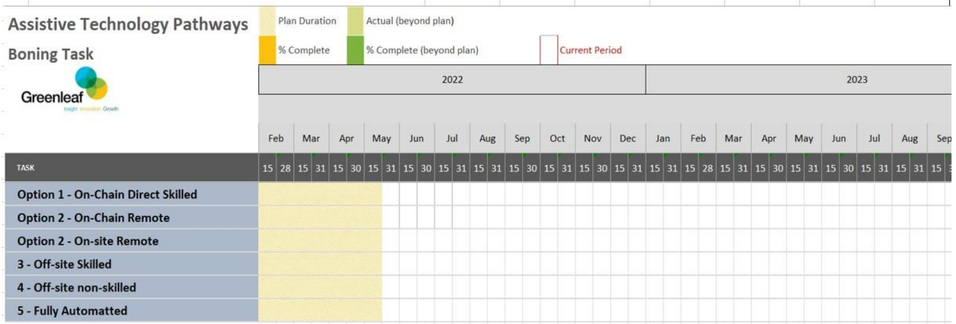


Capability							
Technical							
Direct operator driven Assistive ergonomic power	1						
Human visioning	1	1	1	1	1		
External visioning CCD to inform human		1	1	1	1		
Remote controlled power		1	1	1	1		
Flexible motor controlled arms		1	1	1	1	1	
Feed-back sensing to support accuracy		1	1	1	1	1	
Real-time data transfer speeds		1	1	1	1		
Internet bandwidth speeds				1	1		
Sophisticated real-time image analysis						1	
Internal visioning for muscle seams						0.5	
Enabling							
Training required							
Virtual Training to be developed							
Learning Algorithms collect data for full automation							
Confidence / Engagement							
Product damage risk - system							
Product damage - neglagence / malic							
Solution Complexity							
System Costs							
Value Created ($/hd)							
Labour Jobs saved	$ 0.36	$ 0.36	$ 0.36	$ 0.36	$ 0.36	$ 0.36	
Labour cost / job	$ 0.25	$ 0.25	$ 0.25	$ 0.25	$ 0.25	$ 0.25	
Yield Benefit	$ 2.64	$ 2.64	$ 2.64	$ 2.64	$ 2.64	$ 2.64	
Throughput	$ 7.13	$ 17.11	$ 17.11	$ 17.11	$ 17.11	$ 17.11	
Other							
Total $/hd	**$ 10.38**	**$ 20.36**	**$ 20.36**	**$ 20.36**	**$ 20.36**	**$ 20.36**	

2. **On-farm and/or feedlot – visioning and sensing**
    a. Data capture within current standard practices provides limited incentive to adopt in northern Australia as standalone technologies. Unless methods for additional data capture can be automated such as Body condition score, there is unlikely to be an increase in adoption of basic practices and associated technologies.
    b. Advancement in satellite imagery for Biomass production, coupled with visioning for pasture scanning for ground truthing of this base data, can provide information to improve live animal management practices. However, other information like BCS, more frequent weight gain data among other measures, are all inputs required to generate the extra value.
    c. There is evidence from a number of pastoral companies where lots of time and effort has been exerted in collection of data but for no benefit. Lack of systems and processes, or awareness of what is required to deliver physical change has limited benefit created and has slowed or stopped these initiatives.
    d. Barriers to adoption have not been with the technologies themselves, but how they have been integrated into systems, supported by efficient and effective processes, that make it easy for people to repeat.
    e. Where a combination of new technologies can address the broader barriers, there is more chance of success and broader adoption. A series of integrated solutions have been proposed that prioritise value opportunities, then consider how to integrate these technologies into systems and processes. Opportunity for more integrated solutions that will address multiple barriers to adoption were prioritised. Priority development areas include:
        i. Satellite Biomass prediction, pasture scanning, BCS, weight gains, data integration, staff training in technology support
        ii. Management decision making based on new value propositions based on emerging technologies can enable greater return on assets
        iii.

Development Pathway Options – Extensive Livestock

Problem Space							
Natural resources are not used for best value							
Infrastructure and technoloiges don't support decision making around natural resources as well as they could							
Alignment of resource outputs (livestock) to best markets is difficult to identify, and difficult to align due to lack of infromation to support de							
Labour shortages and high turnover make it difficult to maintain efficient operations							
Stakeholder Pains							
Work in remote areas is not appealing for staff retention due to limited amenities and services							
Rugged environments can compromise repeatible data systems							
It is hard to retain staff that have thorough knowledge of best practice systems and can make processes repeatible							
Lots of data but much of it is not actionable							
Solutions	**Path 1**	**Path 2**	**Path 3**	**Path 4**	**Path 5**	**Path 6**	**Path 7**
Gains	Actionable Biomass Estimation	Crush-side livestock OM	Remote livestock OM	Remote drafting	Automatted drafting		
Automation for labour saving					1		
Remote operation to enable labour attraction			1	1			
Higher value decisions from early knowledge (pre-muster)			1				
Higher value decisions from real-time data integration	1	1	1	1	1		
Refined decision/environment interactions (Feedback loops)							
Aligning livestock to highest value markets							
Labour pool available							
Development timeline to commercialisation							



Capability							
Technical							
Improved Satelite imagery for Bimoass estimation	1						
Integrated data for real-time decisioning	1						
Remote - drafting controls				1			
Real-time visioning for remote operators				1			
Automatted drafting controls							
Visioning to support remote drafting							
Automated Body Conditon Score visioning							
Data integration to access visioning outputs							
Enabling							
Integrated metrics customised to bioeconomic conditions							
Confidence / Engagement							
Size of property and labour challenges will limit intervention							
Options that support smaller propertys							
Solution Complexity							
System Costs							
Value Created ($/hd)							
Labour Jobs saved							
Labour cost / job							
Yield Benefit							
Value Increase (better alignment)							
Throughput							
Other							
Total $/hd	$ -	$ -	$ -	$ -	$ -	$ -	

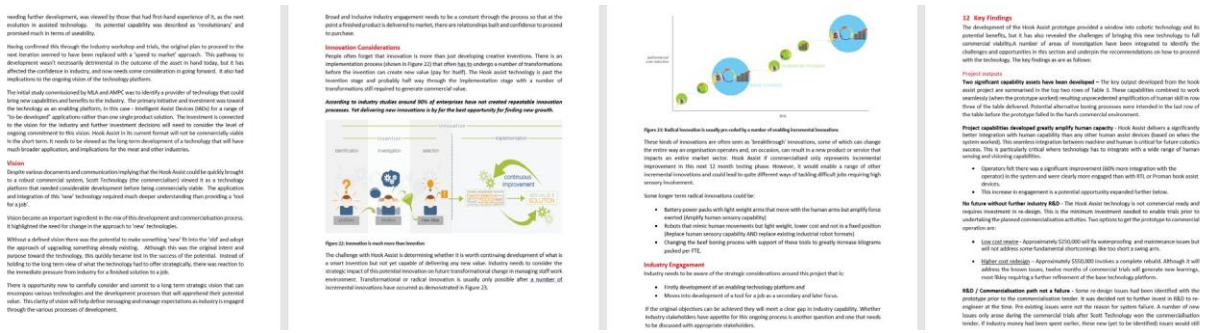
Table 5: Development opportunities for extensive livestock production

3. **Live-animal pre-slaughter** - focused on labour saving and risk management
    a. Knowing which animals will marble at 100d, 400d – which animals give ROI – on feed to give right marbling score for investment in feed

5. Conclusion

5.1 Key findings

- Innovation has a better likelihood of adoption when there is a clear path of progressive development that includes ongoing advancements in capability to address the core problems
- A clear vision of the longer term benefits is required to underpin bigger bolder innovation
- Solving narrow problem spaces does not seem to get the same level of commercial engagement unless the solutions are very simple turnkey
- Innovations on the horizon that will be possible as a result of integration of existing cobotic and visioning technologies will be quite disruptive. To move on these quickly will require a clear roadmap that:
    - Engages all sectors
    - Enables creativity and innovation within a framework
    - Has a very clear focus on problems being addressed
    - Has enough flexibility around the problem space that test and learn methods are free to test and fail quickly without losing focus.
    - Focus on the interaction of problem spaces enables big bolder disruption if commercial entities can be engaged
    - Multiple pathways need to be tested BUT a method for cutting them off early is required. This requires focus on the problem space that creates the greatest value.



Being able to package up a range of incremental innovations with a view to achieving a larger radical innovation is able to be more focused and targeted towards solving a much larger problem. The R&D at each incremental level can then be targeted with more likelihood of achieving the bigger goal.

5.2 Benefits to industry

The Greenleaf supply chain methodology outlined in section 3 – considers following elements:

The many technologies and problem spaces reviewed in this project were passed through a whole of supply chain lens, considering the longer term benefits bigger bolder projects could achieve for industry. Three key development areas were prioritised in on-farm and processing sectors. The development of enabling capabilities required for success in these areas were also considered, and if successful, will underpin successful commercialisation of other future development areas.

Key industry themes:

1. Value based transactions
2. Enhanced operational decision making to increase supply chain alignment to customer needs to improve return on inputs
3. Improved productivity through enhanced capability to address product cost
4. Increased value realised through enhanced capability to supply the highest paying customer for that product

6. Future research and recommendations

Development of collaborative commercialisation projects that begin with the R&D and finish with commercial adoption.

Engage commercial companies that understand the commercial value proposition, and are committed to commercial success.

Develop clear programs of work that have very tight success objectives, and well-defined frameworks that support agile design and pivoting as required, in a way that provides confidence and accountability to the participating stakeholders.

Include the summaries of program scopes for collaborative research and development in the 3 priority areas that address the project findings:

- Commercial
- Agile
- Clear VP agreed with commercialiser
- Engagement in vision

7. References

Tables

Figures

8. Appendix

8.1 Annex A - List of Technologies

The list of technologies that would be researched was initially scripted as the below:

Phase 1 Technology Category List

- Exo-skeleton
- Cobots/Robots
- Manual Assist / Teleoperated
- Full / Semi Automatic Slaughter Line
- Augmented Vision
- Visioning & Sensing- CT
- Visioning & Sensing- X-ray
- Visioning & sensing- MRI
- Visioning & Sensing- Sonic
- Visioning & Sensing- Radio Scan
- Visioning & Sensing- Camera Technology
- Visioning & Sensing- Other
- VR/AR

The above list was formulated upon the original research mandate to consider assistive technologies as a category, and visioning & imaging/sensing technologies as another category. However, after Phase 1 of the research was completed, it became apparent that the research was both too broad (not applied enough to focus on the commercial application of solving industry jobs) and too limited (many of the industry-leading technologies that are prevalent in the above technology categories are too niche and focused in application to be applied to the industry jobs). As a result, an internal review of technology categories was conducted in parallel with a return review on the 'problem (or in this case problems) worth solving), and resulted in the list evolving into the below:

Phase 2 Technology Category List

- Internal AGVs (Automated Guided Vehicle)
- External AGVs
- AGV with robotic arm(s)
- Pneumatic conveying
- CT (small and large bore – boning and quality solution enabler)
- X-ray / DEXA (small footprint)
- NMR/MRI
- Ultrasound
- Hyperspectral
- Microwave
- High Powered Microwave (aka Pain Ray)
- Ultrasonic / laser cutting / CO2 / Water / Ice / Wire
- IoT Device development and evaluation
- Robotics, Cobotics and Manual Assist
- Augmented / Virtual Reality
- Haptic and Remote Control (including Gaming approaches)

- Artificial Intelligence / Deep Learning / Machine Learning
- Isolated/single-purpose automation system (only addresses 1 job type)
- Multi-purpose automation system (addresses multiple job types)
- Camera monitoring & evaluation system
- ID application (e.g. QR code, facial recognition etc.)
- Pneumatics- General (something needs to happen in single place)
- Visioning- General
- Other (details provided where applicable)

Many of the industry jobs could be solved by multiple technologies from the above categories (in the sense of multiple technologies being feasible as stand-alone solutions, or multiple technologies required to form an integrated solution). This analysis was done through internal workshopping, with a spreadsheet output identifying which technologies are relevant for each job, and detail recorded regarding what the solution could look like based on the problem the solution solves.

8.2Annex B - List of Jobs

1. **Processing Jobs**

- Slaughter (Bovine, Ovine, Caprine, All)
    i. Lairage livestock movement (automated – aka pigs)
    ii. Stunning
    iii. Head grading station
    iv. Rinse and Chill Validation
    v. Extremity removal (head, hock and tail)
    vi. Shackling
    vii. Y-Cutting
    viii. DeDagging (lairage and processing)
    ix. Bung Removal (and cleaning)
    x. Hide removal (What parts can we do here)
    xi. Brisket cutting and opening
    xii. Tipping (automated or alternative approach)
    xiii. Evisceration
    xiv. Splitting
    xv. Spinal cord removal
    xvi. Kidney fat removal
    xvii. Hot feather bone separation (and removal)
    xviii. Sterilisation
    xix. Skin on Bovine Processing (dirty side slaughter floor
    xx. Hot carcase grading
    xxi. Hot Grading station
- Boning - Beef
    i. Primal Cutting/Scribing (Treat as 3-4 carcase parts aka lamb)
    ii. Middle Processing (Parts 2 & 3)
    iii. FQ Processing (Part 1)
    iv. HQ processing (Part 4)
    v. Bone Belt Monitoring product loss minimisation
    vi. Trim Sortation (CL) Hot/Chilled
- Boning - Lamb
    i. Primal Cutting (small footprint)
    ii. Aitchbone removal
    iii. Tunnel boning
    iv. Frenching
    v. Fat cap removal
    vi. FQ deboning
- Boning - Goat (& Mutton)
    i. Six/Eight way cutting
    ii. Cubing
- Carcase Chilling
    i. Automated sorting
    ii. Hot boning plant – Middle chilling (i.e FQ/HQ boned hot)

- Pick and Pack (and primal bagging)
    i. Primal identification – naked and bagged (enabler)
    ii. Auto Primal bagging outcomes (auto bagging / wrapping)
    iii. Automated carton packing (and validation)
    iv. Carton packing validation (primal ID and fill/voids)
    v. Vaccum bag leak detection
    vi. Lamb & Mutton Carcase Bagging (and Beef Quarter)
    vii. Carton Handling
    viii. Depalletising and Port marking
    ix. Container loading
    x. Case Buffer, sequencing, mixed case palletising
    xi. Meat lumping (internal and external to plant)
    xii. Label to Product to Carton Integrity
    xiii. Benchmarking (and further evaluating if required) roller/gambrel RFID (or equivalent) slaughter traceability
    xiv. Head processing
    xv. Transmissible Disease protection and monitoring
    xvi. Transmissible Disease protection and monitoring
    xvii. Co-Product Processing
    xviii. Beef feet processing
    xix. Assisted and Automated offal inspection
    xx. Hide grading, sorting and palletising
    xxi. Rendering alternatives
    xxii. Carcase Insection & Trimming
- Carton Handling
- Product and Material Handling
- Traceability & Integrity (A Boning Room focus)
- Co-Product Processing
- People Safety

2. Feedlot Jobs
    - Feed production & Delivery
        i. Receival of grain
        ii. Silage production
        iii. Ration batching/mixing
        iv. Ration delivery
        v. Bunk calling
    - Animal receival & induction
        i. Unloading trucks
        ii. Placing hay in holding yards
        iii. Pushing cattle up in the race
        iv. Catching in the crush
        v. Animal health treatments

    vi. Drafting animals
    vii. Delivery of animals to the pen
    viii. OM data collection to better drafting of animals for feeding programs

- Animal health identification & treatment
    i. Identification of sick animals in the pen
    ii. Movement of animals to the hospital
    iii. Animal health treatments at hospital
    iv. Heat Stress management
    v. Relocation of animals back home.
    vi. Deaths & burial management
    vii. WHS & ESI identification of animals in the feedlot
- Animal movements
    i. To and from receival and exit yards
    ii. Weighing of animals at entry and exit
    iii. Animals lost in the feedlot (going to wrong place)
- Water management
    i. Cleaning troughs
    ii. Leaks identification
- Pen floor improvements
    i. Cleaning out pens
    ii. Processing of manure for fertiliser
- Data collection opportunities
    i. In pen weight gains for feed conversion & intake data
    ii. OM data
    iii. Animal health in pen data

3. On Farm Jobs
- Cattle Yards
    i. Animal movement through yards
    ii. Automated dehorning
    iii. Castration
    iv. Branding (for animal ID)
    v. Ear tags (for animal ID)
- Sheep yards
    i. Crutching
    ii. Shearing
    iii. Marking
    iv. Fodder management
- Operations
    i. Biomass monitoring
    ii. Vegetation management
    iii. Carbon sequestration processors
    iv. Irrigation
    v. Moisture management
    vi. Nutrient management

vii. Animal movement between paddocks
viii. Selection of animals for sale
ix. Pest management
x. Feed monitoring
xi. Water monitoring

- Heavy lifting operations
    i. Fencing

8.3 Annex C - List of Companies

List of Assistive / Cobotics Companies:

1. 6River- a mid-sized company operating globally, focusing on high-load exo-skeleton technology with a industrial, warehouse & logistical industry focus. Strong revenue growth and partnerships indicative of the optimism surrounding start-ups.
2. Lyro – a small local company from Australia, focusing on robotic automated packaging solutions utilizing visioning for a retail and industrial focus. A market-leader in research and technology for logistics and warehousing solutions for agricultural industry. Award winning team and research/technology/business advisors with globally recognized experience.
3. Ocado Group – is a large innovative, one-of-a-kind company with presence in a couple countries so far; 10 partners so far. They have created a system/chain for mass, online grocery shopping and ordering focusing on retail. Is the world's 2nd largest retail platform as a globally present innovator.
4. Dematic – World's 2nd largest materials handling systems supplier with a focus on AGV's in warehouses that are collaborative. Their headspace is in retail, industrial, mining, aviation and logistics, agriculture and automotive industry
5. Direct Industry – a B2B marketplace for industrial equipment, not a product manufacturer.
6. Ebn Online – an industry expert on key industry questions, not a product manufacturer.
7. Kawasaki – a large global leading robotics company with growth and engagement across multiple industries: public interface, retail, industrial, aviation and logistics, agriculture, automotive, mobility. Dabbles in cobotics. Humanoid robots focused on automated factories and collaborative arms.
8. Universal Robot – a large global leading cobotic arm company with a developed business approach. A market-leading company in cobotics with a focus on workflow enhancement of companies in retail, artisan and industrial.
9. Fanuc – one of the largest global leading robotics company with growth and engagement across multiple industries. Focus on robot arms, plus manufacturing machines. Moving into the cobotics industry, mainly an innovator in large payload robots.
10. Easy Robotics – a small niche independent company that works on robotic stations for machine tending in the robotic industry and has their foot in the pharmaceutical, aviation and logistics, agriculture and automotive, mobility industry.
11. Doosan – similar to universal robot and is a competitor in the cobotics industry, but with a focus on R&D and sustainable growth of company. An industry focus in construction, industrial, mining.
12. ABB – a very large company with a leading approach to many industries in automation: Retail, Construction, Minig, Security, Automation. They specialize in cobotic arms for assistive workflows and support small businesses and pharmaceutical workflows. They also provide solutions for many other non-automative industries. Possess a large body of knowledge in the tech solutions industry.
13. Akon – a very small company in Europe who specialize in egg palettizing automation. One of many companies who utilize existing robotic arm solutions from leading solutions providers to integrate into commercial ready specific automotive solutions in the agricultural industry.
14. Nachi – a medium sized global company in the robotics industry providing robotic arm solutions for automation. Strong performer with a focus in construction, retail, industrial, agriculture.

15. Kuka – is a leading global innovator in the robotics industry with a focus towards assistive and cobotic arms. They are a large company with a focus towards the medical, construction, retail, industrial, mining, aviation and logistics, agriculture, automative and mobility.
16. Yaskawa – is a leading global innovator in the robotic arm industry with a focus for every robotic application in the industry. There smart series have rolled out with 4 designs.
17. OCRobotics – is a small global leading company in visioning and robotics to assist with inspection and maintenance of remote access sites. They are an R&D company with a working product and a focus in construction, artisan, industrial, mining, aviation and logistics, automotive and mobility.
18. RoboWorld – provides suits & protective equipment for robots to prevent wear & tear.
19. Staubli – No.7 in world's top ten industrial robot manufacturers and is a large global leader. A very focused product range with collaborative and AGVs and general robot arms targeted at all automated industries.
20. DanskRobotTeknik – not a product manufacturer- distributes & integrates market-leading robots into an integrated solution + installs solution for clients.
21. Intuitive Surgical – The most dominant medical robotics company with global reach and increasingly utilized systems for surgeries. 20 years of software development capabilities
22. Auris – a small-medium starting up US company focused on medical robotic assisted surgery. Partnered with Johnson & Johnson and focusing on user interface and experience for physicians.
23. Medtronic – Largest medical company that is in the robotic assisted surgery space as well as many other forms of healthcare. Focus is more so on healthcare than technology development. Similar products to intuitive and Auris.
24. Stryker – provides the vast majority of medical equipment used by physicians and is a global leader in the space. They have a system for robotically assisted surgery
25. Corindus – is a small technology centred siemens healthcare company working on robotic assisted surgery for specific type of surgical application in the US. Leader in niche technology provided.
26. Asensus – a small starting company with a robotic assisted surgical system looking to boost its business with it's similar approach to Auris and Intuitive Surgical. Specific global locations.
27. Titan Medical – a small US company startup with a high focus on it's technology rather than healthcare applications. Looking to increase popularity through design. Is partnered with Medtronic.
28. Stereotaxis – is a small/medium company focused on visioning technology and robotically controlled imaging. Is a global leader in it's industry niche
29. Smith & nephew – a large global leading company in the healthcare industry with a focus on injuries and patient care. Developed a smart AI/robotic assisted technology for surgery; focused on healthcare.
30. ZimmerBiomet – a competitor to smith and nephew with the same focus, utilizing real robotic/collaborative arms for assistance in surgery.
31. Vicarious Surgical – Boston-based company focused on research and development of highly flexible robotic assisted surgery. A small niche company, not yet public
32. Vicarious AI – Canada-based company focused on providing automated solutions for companies in the picking industry. Utilizing robots for automation. A small niche company
33. Monteris – a small US company providing solutions for minimally invasive technology utilizing robotics and MRIs. 20 years in the healthcare industry.
34. Marel – A leading global provider for advanced food processing and scanning. Very large company with a focus in public interface, retail, agriculture and cold chair.

35. Ekso Bionics – a small company with a presence in the automotive industry as an injury-prevention provider via their bionic suits. One of the leading R&D companies in the space.
36. Makinex –

List of Visioning / Imaging Companies

1. VSight UAB
2. ThirdEye
3. Toshiba
4. Vuzix
5. Teamviewer Frontline
6. Epson
7. Analogic
8. Rapiscan
9. Smiths Detection
10. L3Harris
11. IDSS
12. Inutitive Surgical
13. Esaote
14. Carestream
15. Frontmatec
16. ScopeAR
17. EverySight
18. Solos
19. Spatial
20. Liminal VR
21. Teslasuit
22. HTC Vive
23. Oculus
24. Fujifilm Holdings
25. GE Healthcare
26. Siemens Helthcare
27. Minfound
28. NeuroLogic
29. Neusoft
30. Epica
31. 4DDI
32. Eagle x-ray
33. Nutech
34. GIG XR
35. Engage
36. C360
37. SLAMcore

38. Sonic Healthcare
39. iTechArt
40. Shimadzu Corporation

8.4Annex D - Database of systems created as part of this project

Preliminary research has been undertaken as part of milestone 2 and 3 in this project. This has helped form up the methodology required to assess technologies and their applicability to the red-meat industry.

Further to this, discussions with MLA in the first milestone have highlighted the need to work with MLA in milestone 3 to consolidate previous MLA projects and findings into this assessment to avoid duplication and to have an integrated outcome that can assist other MLA program areas.

Technologies

#	Name	Category	Images	Vendor	Description	Commercial ready
Category: Exo-Skeletons						
1	Sarcos Guardian® XO® Full-Body Powered Exoskeleton	Exo-Skeletons		Sarcos Robotics	The Sarcos Guardian XO full-body, powered exoskeleton is a first-of-its-kind wearable robot that enhances human productivity while keeping workers safe from strain or injury. Set to transform the way work gets done, the Guardian XO exoskeleton ...	✔
2	backX by suitX	Exo-Skeletons		suitX		✔
3	legX by suitX	Exo-Skeletons		suitX		✔
4	shoulderX	Exo-Skeletons		suitX		✔
5	PERCRO Body Extender - whole body exoskeleton for human power augmentation	Exo-Skeletons	 	PERCRO	[2012] An advanced wearable robot expressly conceived for augmenting the human strength for handling of heavy materials in unstructured environment. The system is composed by four robotic limbs with anthropomorphic kinematics and has a tota...	
Category: Cobots / Robots						
6	UNIVERSAL ROBOT UR3e	Cobots / Robots		Universal Robots	The UR3e collaborative robot is a smaller collaborative table-top robot, perfect for light assembly tasks and automated workbench scenarios. The compact table-top cobot weighs only 24.3 lbs (11 kg), but has a payload of 6.6 lbs (3 kg), ±360-degree ...	✔

#	Name	Category	Images	Vendor	Description	Commercial ready
7	UNIVERSAL ROBOT UR5e	Cobots / Robots		Universal Robots	THE UR5e - A FLEXIBLE COLLABORATIVE ROBOT ARM Built with the future in mind, the UR5e is designed to grow in capability alongside your business, a spring board to improved product quality and productivity, so you wil...	✔
8	UNIVERSAL ROBOT UR10e	Cobots / Robots		Universal Robots	The Universal Robots UR10e is an extremely versatile collaborative industrial robot arm with its high payload (10kg) and long reach capability. Its 1300mm reach spans wide workspaces without compromising precision or payload performance. UR10e addresses ...	✔
9	Frontmatec automatic lamb shoulder machine	Cobots / Robots		Frontmatec	Processes complete lamb shoulders (double). After the shoulder has been positioned in the machine, it automatically cuts off the two front shanks. The circular knives are automatically adjustable in height. ...	
10	Frontmatec AiRA Robotics	Cobots / Robots		Frontmatec	Frontmatec offers a complete program of AiRA dressing line robots. The AiRA robots is a concept based on more than 20 years of R&D in engineering of automated processing and is regarded as the world's unrivaled leader in dressing line robotics. T...	✔
11	UNIVERSAL ROBOT UR16e [NEW]	Cobots / Robots		Universal Robots	The Universal Robots UR16e delivers an impressive 16kg (35.3 lbs.) of payload within a small footprint, and is ideal for use in heavy machine tending, material handling, packaging, and screw and nut driving applications. This powerhouse robot allows ...	✔
12	DOOSAN M-SERIES (M0609 · M0617 · M1013 · M1509) [Masterpiece]	Cobots / Robots		Doosan	M-SERIES is the highest quality premium cobot! 6 high-tech torque sensors provide the highest dexterity for highly sophisticated tasks and ensure the upmost safety...	✔
13	DOOSAN A-SERIES (A0509 · A0509s · A0912 · A0912s) [Almighty]	Cobots / Robots		Doosan	A-SERIES can go anywhere! With its superior speed and cost-effectiveness, A-SERIES promises a simple solution and a satisfaction to whom may be hesitant to get a cobot	✔

#	Name	Category	Images	Vendor	Description	Commercial ready
14	DOOSAN H-SERIES (H2017 • H2515) [High-Power]	Cobots / Robots		Doosan	H-SERIES is the most powerful cobot in the market. Outstanding 25kg payload and 6 torque sensors brings safe work environment for any kind of application	✔
15	YF002N - Kawasaki Robotics for food processing	Cobots / Robots		Kawasaki Robotics	The YF002N pick & place robot is the compact model of the Y series and it can be installed in narrow spaces. The high-speed Y series Robots can be used for material handling and assembly applications in a variety of industries, including food, ...	✔
16	duAro2 - Kawasaki Robotics for food processing	Cobots / Robots		Kawasaki Robotics	The Dual-Arm SCARA Robot "duAro": A brand new offering that realizes the concept of an innovative dual-arm SCARA robot which can safely collaborate with humans in work operations. The duAro2 has the deeper vertical stroke ...	✔
17	FANUC - food and beverage robots	Cobots / Robots		Fanuc	We have the largest offering of standard and collaborative robot models with payload capabilities from 0.5 - 2,300 kg. In addition, we provide application software for packaging and palletizing, integrated iRVision® and tracking features, ROBOGUI...	✔
18	PickRobot (single, double, triple, quadruple, SmartPicker	Cobots / Robots		weber	The Weber PickRobot stands for the uncompromising automation of slicing applications. Specifically adapted to your application area, it can be used flexibly for all insertion tasks and is available in five different executions: SmartPicker, single, ...	✔
Category: Manual Assist / Teleoperated						
19	Guardian® XT	Manual Assist / Teleoper...		Sarcos Robotics	The Guardian XT teleoperated dexterous robot performs intricate, and even dangerous, tasks that require human-like skill, all while keeping the operator at a safe distance. The robot is platform-agnostic and attaches to various mobile bases, including ...	✔
20	Talon® Series Pick-and-Place Robots Packing System	Manual Assist / Teleoper...		JLS Automation	Hygienic Robotic Packaging Solutions	✔

#	Name	Category	Images	Vendor	Description	Commercial ready
21	Osprey® Robotic Case Packers	Manual Assist / Teleoper...		JLS Automation	Osprey® Robotic Case Packers are designed for washdown applications such as meat, poultry, fresh produce, frozen (IQF) foods and cheese.	✔
22	QuickPick 201 3D Vision Guidance System	Manual Assist / Teleoper...		Visual Robotics	Visual Robotics' QuickPick 201 3D Vision Guidance System is a transformational offering. With our patent-pending Vision-in-Motion™ technology, a robot can track and handle moving objects as easily as static. No conveyor instrumentation. No gantry ...	✔
Category: Augmented vision						
23	[Headset] VUZIX M series Smart Glasses	Augmented vision		Vuzix		✔
24	[Software] xPick - Vision Picking solution	Augmented vision		Teamviewer Frontline	xPick is a patented and award-winning "pick-by-vision" solution. It supports manual order picking, incoming, outgoing, and sorting of goods, inventory control, sequencing, and many more processes in logistics and warehousing.	✔
25	[Headset] Moverio BT-200 Smart Glasses (Developer Version Only) CLOSEOUT	Augmented vision		EPSON	Enhanced features in accessories, lens and controllers; works out-of the-box with most Android apps	✔
Category: Visioning & Sensing - CT, X-ray						
26	eXaminer® XLB - CT-based ultra-high-speed explosives detection system	Visioning & Sensing - CT...		Analogic L3Harris	High-Speed Explosives Threat Detection for Large, Heavily Travelled Airports Key Features of the eXaminer XLB: Innovative PowerLink™ brushless power ...	✔

#	Name	Category	Images	Vendor	Description	Commercial ready
27	Analogic ConneCT	Visioning & Sensing - CT...	 	Analogic	ConneCT features a new modular imaging system based on advanced medical imaging technology and an interoperable network architecture designed to maximize reliability and achieve the lowest total cost of ownership.	✔
28	RTT110	Visioning & Sensing - CT...	 	Rapiscan	The RTT® is designed to allow screening to the highest levels of security at the first point of screening. The versatility of RTT allows it to be used as a high speed in-line system at the first level of screening or as a level 3 ...	✔
29	CTX 5800	Visioning & Sensing - CT...	 	Smiths Detection	CT explosives detection system A compact explosives detection system (EDS), the CTX 5800 identifies threats in checked baggage and cargo packages. ...	✔
30	CTX 9800 DSi	Visioning & Sensing - CT...		Smiths Detection	High speed CT explosives detection system The CTX 9800 DSi explosive detection system (EDS) uses a proprietary single X-ray source, dual energy design that provides high-resolution 3D images along with 2D and 3D...	✔
31	L3 ClearScan® Checkpoint CT	Visioning & Sensing - CT...		L3Harris	The L3 ClearScan® cabin baggage screener uses CT technology and advanced algorithms to deliver the highest level of explosives threat detection at an unprecedented false alarm rate. The aviation security system is designed to detect solid and liquid ...	✔
32	DETECT™ 1000	Visioning & Sensing - CT...		IDSS	Based on medical computed tomography (CT) imaging technology, the DETECT™ 1000 is a powerful lens with which to see and identify smaller and more advanced threats than ever before. ...	✔
33	Da Vinci Vision – Iris (part of Da Vinci Surgical Systems)	Visioning & Sensing - CT...		Intuitive	Iris is an anatomical visualization service that makes it possible for you to bring your surgical plans into the operating room. Using data from diagnostic CT imaging, a segmented 3D model of your patient's anatomy is created. Iris then enables you to...	✔

#	Name	Category	Images	Vendor	Description	Commercial ready
34	EquImagine – 4D true sterro-Dynamic 4D scanning	Visioning & Sensing - CT...		Universal Medical Syster	High accuracy, shows where bones are and a couple other things too, they also have a large CT animal scanner (http://www.veterinary-imaging.com/multi-slice-ct.php)	✔
35	[X-ray] DRX-Revolution Mobile X-ray System	Visioning & Sensing - CT...	 	Carestream Health	A mobile X-ray system on wheels powered by a wireless DRX detector. Ultra-manoeuvrable, automatic, collapsible column mobile imaging system.	✔
36	[X-ray] CPS-X 400 X-ray Scanner	Visioning & Sensing - CT...			The products get transferred in a continuous-flow process. Products go through the scanner where the mass allocation of each product is determined using X-ray technology. The products are then weighed on the integrated weighing ...	✔
37	[X-ray] Multitom Rax – robotic arm x-ray	Visioning & Sensing - CT...			It is particularly suited for difficult exams such as trauma or orthopaedic cases. Benefit from unique insights, efficient workflows, as well as comprehensive diagnosis on a single system – and set new standards in advanced musculoskeletal and trauma imaging. Preci...	✔
Category: Visioning & Sensing - Other						
38	Beef Classification Center, BCC-3™ (Advanced multi-view stereo imaging)	Visioning & Sensing - Ot...	  	Frontmatec		
Category: Full / Semi Automatic Slaughter Line						
39	HAMDAS-RX Automatic Ham Boning Robot	Full / Semi Automatic Sla...	 	Mayekawa (MYCOM)	The world's first automated ham deboning robotic machine. HAMDAS-RX automatically debones pork ham after pre-cutting is performed. The auto measuring feature allows precision cuts to the correct specifications of each ham and provides ...	✔

#	Name	Category	Images	Vendor	Description	Commercial ready
40	WANDAS-RX Automatic Pork Shoulder Deboning Machine	Full / Semi Automatic Sla...	 	Mayekawa (MYCOM)	An automated pork shoulder deboning robotic machine, the WANDAS-RX. It utilizes the technology of the HAMDAS-RX. Our image processing and auto measuring features with a vertical multi jointed robotic arm allows WANDAS-RX to process precisio...	✔
41	FALCON smartline by TREIF and Meral	Full / Semi Automatic Sla...		TREIF Marel	Less personnel — More flexibility — All from one source Simply faster to the finish line — with Smartline Your products are processed with nearly 10...	
42	OSAINT Chicken Slaughtering Line	Full / Semi Automatic Sla...	 	Shandong Osaint Machi	Complete Chicken Slaughtering Line for chicken killing, scalding, plucker, visceral and cut up	✔
43	LEAP (Low investment, Expandable, (semi) Automatic Processing) Concept - Chicken Slaughtering Line	Full / Semi Automatic Sla...		Meyn (subsidiary of CTB	The Leap concept incorporates Meyn's top-of-the-line technology at all stages. Expand from 500/1,300 to 15,000 bph.	✔
44	Poultry processing line 6000 birds per hour with auto Evisceration	Full / Semi Automatic Sla...	 	Dutch Poultry Tech	6000 birds per hour poultry processing line. Based on proven technology and 30 years of poultry processing experience. Lean engineering, manufacturing and overhead enable a cost-effective processing solution. Low initial investment, low cost of ownershi...	✔
45	Danish Crown Pork Processing Plant	Full / Semi Automatic Sla...	 	Frontmatec	• Automatic bung cutter, throat cutter and ham divider (APOLLO) • Automatic carcass opener (OMEGA) • Automatic evisceration (ORION) • Automatic back finning (pre-cutting of loins) (SATURN)...	✔
46	Cattle Slaughterhouse Systems & Equipments (HALAL)	Full / Semi Automatic Sla...		CEMSAN Slaughterhous		

#	Name	Category	Images	Vendor	Description	Commercial ready
47	Sheep Slaughterhouse Systems & Equipments (HALAL)	Full / Semi Automatic Sla...		CEMSAN Slaughterhous		

8.5Annex D - Companies

Company capabilities will be populated based on business model canvas viability aspects, as well as technology capabilities. Which companies are most likely to align themselves with the Australian red-meat industry for development of horizon 2 and 3 technologies.

#	Name	Logo	website	Headquarter	Countries have office	AU Office	Contact	Distributor / Position
1	Analogic		https://www.analogic.com/	US			LeeAnn Levesque	Security CT Sales and Media Inquiries
2	Avante Health Solutions		https://avantehs.com/c/ct-scanner-machine/1113	US			Jasen Hargrove	International Sales for Southeast Asia, Canada, Europe
3	Carestream Health		https://www.carestream.com/en/us/	US		Level 3 176 Wellington Pde East Melbourne, 3002 Australia		
4	CEMSAN Slaughterhouse Systems		http://www.cemsanmakina.com/en/	Turkey				
5	Doosan		https://www.doosanrobotics.com/en/Index	Korea		11A Columbia Way, Baulkham Hills, New South Wales 2153		Doosan Bobcat Doosan International Australia Pty Ltd.
6	Dutch Poultry Tech		https://www.dutch-poultry-tech.com/	Netherlands				
7	Easy Robotics		https://www.easyrobotics.biz/	Denmark				
8	EPSON		https://epson.com/usa	US		Unit 4C, 305 Montague Rd, West End, Qld 4101		
9	Fanuc		https://www.fanuc.com/product/index.html	Japan		Unit 6, 29 Cinderella Dr, Springwood, QLD4127, ...		FANUC Oceania
10	Frontmatec		https://www.frontmatec.com/en/front-page	Germany				

#	Name	Logo	website	Headquarter	Countries have office	AU Office	Contact	Distributor / Position
11	IDSS	IDSS Integrated Defense & Security Solutions	https://www.idsscorp.net/en/airport-security	US				
12	Intuitive	INTUITIVE	https://www.intuitive.com/en-us	US		Garigal Road, Belrose, NSW-2085, Australia		Distributor - Device Technologies Australia Pty Ltd.
13	JLS Automation	JLS	https://www.jlsautomation.com/	US				
14	Kawasaki Robotics	Kawasaki Robotics	https://robotics.kawasaki.com/en1/industries/robots-for-beverage-automation/	Japan				Distributor - Diverseco Brisbane South Branch
15	L3Harris	L3HARRIS	https://www.l3harris.com/en-au/australia?regional_redirect=en-au	US		Level 1, 97 Northbourne Avenue, Turner ACT 2612		L3Harris Australia
16	LYRO	LYRO	https://lyro.io/	AU		6 Electronics St, Eight Mile Plains QLD 4113		
17	Marel	marel	https://marel.com/en	Iceland		42 Borthwick Ave, Murarrie QLD 4172		Marel Food Systems Pty Ltd. AU
18	Mayekawa (MYCOM)	MAYEKAWA MYCOM	https://www.mayekawa.com/	Japan		Unit 2, 44 McCauley Street, Matraville, NSW 2036		MAYEKAWA Australia Pty Ltd
19	Meyn (subsidiary of CTB Inc.)	meyn	https://www.meyn.com/	Netherlands				
20	PERCRO	PERCRO Perceptual Robotics Laboratory	https://www.santannapisa.it/en/institute/tecip/perceptual-robotics-percro-lab	Italy				
21	Rapiscan	Rapiscan systems An OSI Systems Company	https://www.rapiscansystems.com/en/	US		6-8 Herbert Street, Unit 27, St. Leonards, NSW 2065		Rapiscan Systems Pty Ltd

#	Name	Logo	website	Headquarter	Countries have office	AU Office	Contact	Distributor / Position
22	Sarcos Robotics		https://www.sarcos.com/	US				
23	Shandong Osaint Machine Co., Ltd		https://www.osaintequipment.com/	China				
24	Siemens Healthineers		https://www.siemens-healthineers.com/en-au#05664149	Germany		885 Mountain Highway, Bayswater, VIC 3153		
25	Smiths Detection		https://www.smithsdetection.com/	UK		Unit 5 Botany Grove Estate, 14A Baker St, Botany, NSW ...		Smiths Detection (Australia) Pty Ltd
26	suitX		https://www.suitx.com/	US		117B Great Eastern Hwy, Rivervale WA 6103	Ruth Lennon	Distributor - Biosymm https://www.lifereadybiosymm.com/
27	Teamviewer Frontline		https://www.teamviewer.com/en-us/solutions/frontline/	Germany				
28	TREIF		https://treifusa.com/	Germany		2/7 Jubilee Ave, Warriewood, NSW 2102		Distributor - CBS Foodtech Pty Ltd https://cbsfoodtech.com.au/brands/treif/
29	Universal Medical Systems		https://www.universalmedsystems.com/	US				
30	Universal Robots		https://www.universal-robots.com/	Denmark			Oceania sales rep. in Singapore	https://www.universal-robots.com/distributors/#/map/2514/26086/-/-
31	Visual Robotics		https://www.visualrobotics.com/	US				https://www.visualrobotics.com/contact-1
32	Vuzix		https://www.vuzix.com/	US				https://www.vuzix.com/Contact/Saless

#	Name	Logo	website	Headquarter	Countries have office	AU Office	Contact	Distributor / Position
33	weber		https://www.weberweb.com/	Germany				
						FILLED 14		

8.6 Annex F – Workshops

Commercial application scoping and ideation is the gap between desktop scoping and commercialisation. At the later end of the feasibility stage practical application of solutions into commercial environments is to be assessed. Given the limited time in the project, this will be done as 1 to 2 site visits with processors and producers to consider the barriers and challenges involved in integrating technologies into commercial environments. The workshop purpose and methodology are outlined in the sections below. The findings from these workshops will be populated into the assessment matrix and reported in findings.

Review process flows

The process flow review looks to outline the specific applications and process flow options using the current as a baseline and looking and methods to change the current process flow for future benefits. Process flows will be presented – (format below is an example only) BUT will be accompanied by product photo's, value metrics, challenges and risks at each stage that need to be addressed. This detail will support tests that feed into work plans.

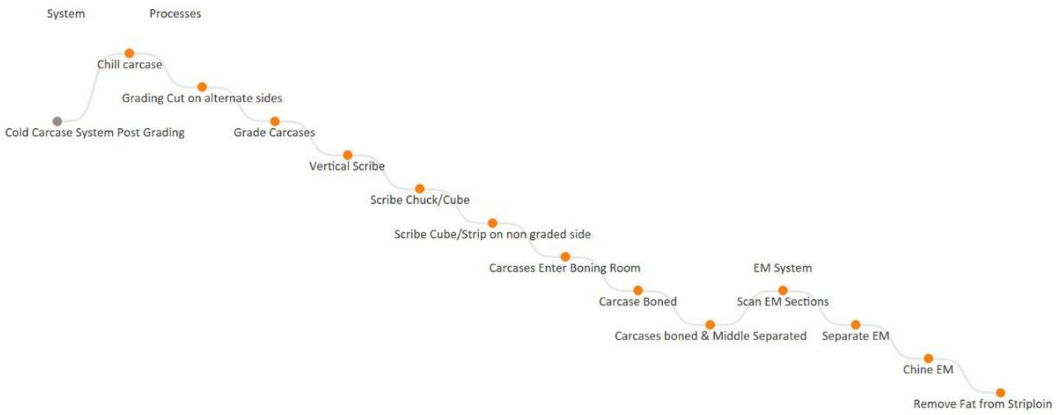


Figure 9: Example process flow

NOTE – there will not be one single process flow. Multiple prioritised flows/cutting approaches will be maintained as pivot options for service providers depending on ease of engineering of deliverables.

Technology Capabilities

The objective of this activity is to imagine how technology could deliver the solutions from step 2. Technologies will be presented for each cutting line or combination of boning processes with examples of capability.

A number of questions will be pre-prepared to be answered during product brainstorming on-site in the next step.

Although the focus is on technology the groups skill sets are still operational and task focused rather than engineering service provider focused. This is to:

- prevent narrowing of focus to one particular service providers skill sets

- Develop workplan of activities as blocks of design work – this will be prepared to then engage technology service providers in.

An automation expert and an assistive technology (cobotics) expert will be attending (Yet to be confirmed – potentially via video link subject to travel restrictions) and will lead parts of this section in censoring what is possible/commercially realistic. They will bring alternative approaches that stimulate operational solutions to align with existing technology capabilities.

The discussion may prompt further ideas on carcase breakdown, integration, or other risks not yet thought of. This will aid the hands-on boning room breakdown session in the next step. Technology examples will be presented for each of the following areas:

a. Cobotic assistive technologies
b. Automated cutting capabilities
c. Visioning technologies
d. Clamping capabilities

Figure 10: Example visioning systems and assistive technology integrations for discussion

Product inspection

A range of different engineering designs will be investigated. The intention is to show how each application could be done, and how a combination of cuts could be integrated. Different applications of technology/cutting outputs will have different impacts on capital cost, integration with existing boning layouts, performance (yield, throughput, labour, ROI)

Workflows and outputs will be broken down, disassembled, then reassembled to support the discussion process.

The impact of technologies on each process flow will be discussed as the task components and the flow in the boning chain are used to pressure test the options for automation.

Minimum levels of improvement that warrant development will be agreed. For example, a small improvement in shoulder boning using Cobotics will be assessed in relation to overall process integration as worthy or not for development. Manually assisted lifting on pastoral property or visioning of crush side activities may or may not benefit the overall processes required of people. Pros and cons of each automation scenario within the whole process flow will be considered.

8.7 Annex G - Business case analysis modelling

The following outlines the 5-step approach Greenleaf has used on previous projects to calculate the value created through increased accuracy of cutting lines through automation. The benefits derived from other processors will be assessed and a similar method will be developed where appropriate. The level of detail included for each application will be assessed in association with the budget and potential benefits from the application.

Accuracy standards (mm = grams meat)

The models utilise the standard assumption of 1.033 g/cm3 of meat density to volume. This provides the conversion of meat volume calculations to a kg weight from which a $ value can be determined using adjusted yields from each application

Cutting line accuracy (Manual, CT & DEXA)

A cutting line accuracy measurement of will be assumed for each application throughout the calculations process for the new automated process.

Carcase variables (EMA, fat depth etc)

Eye Muscle Area (EMA) assumptions and models were used to determine appropriate meat areas for product volume calculations. The general form of the volume calculation is EMA at x depth of cut or accuracy measure.

Price differentials ($)

Differential prices based on historical yields for each plant were determined using industry reporting data. The price differentials were calculated for different product cuts as well as different animal feed types. The final model provides the ability to undertake scenario modelling for different animal process composition and volumes (with automatically adjusted yields), to help stress test the investments for the automation processes.

Impact on value opportunity (IRR%)

The full marginal impact of the investment, for each plant, was modelled using the accuracy model inputs previously described as well as assumptions regarding volume and percentage of animal feed types processed through the three plants.

It is important to note that a reasonable expectation from automation would be an increase in throughput and so the modelled scenarios allow for a once off increase in plant production volumes, for each plant, because of investing in an assumed automation process.

To maintain the integrity of the investment decisioning, the models permit "switching off" the automation benefits of each or all the cuts modelled. This can be different for each plant being modelled.

To determine the payback period, marginal cashflow and IRR for each plant, 10-year assumptions regarding additional capital investment, upgrade and support costs were included. Assumptions regarding savings from labour, OH&S and throughput were also captured. All can be adjusted based on the investment appetite and expectations to determine a complete marginal position from the investment.

8.8 Annex H - Research for Milestone 2

The visioning systems outlined in this section and the cobotic or manual assist technologies summarised in section 9 will be integrated into the assessment methodology outlined earlier along with additional criteria to be expanded out for each company for each capability area.

1.1 Computer Tomography (CT)

1.1.1 eXaminer® XLB - CT-based ultra-high-speed explosives detection system EC

Category

CT, commercial continuous throughput

Brief description

High-Speed Explosives Threat Detection for Large, Heavily Travelled Airports

Key Features of the eXaminer XLB:

- Innovative PowerLink™ brushless power transmission system
- Throughput of up to 1,200 bags per hour in Continuous-Flow mode
- One-meter-wide tunnel
- TSA certified EDS

Industry

Aviation, already been used in some airports

Company

Analogic & L3harris

System specifications

(Product brochure)

- Throughput speed: 1,200 bags per hour
- Weight:
    - Scanner: Approx. 5,035 kg (11,100 lbs)
    - Inline Entry/Exit Tunnel: Approx. 771 kg (1,700 lbs)
- Dimensions:
    - System Dimensions: 528 cm (208") L x 224 cm (88.2") H x 228 cm (90") W
    - Conveyor Belt Height: 947.7 mm (37.3")
    - Conveyor Speed: 34 cm/sec (13.4 in/sec)
    - Conveyor Capacity: 136 kg (300 lbs)
- Image resolution:
    - Video Resolution: Dual 1600 x 1200 high-resolution, flat panel LCD monitors
    - Image Display: High-resolution 2-D and 3-D images Enhanced 3-D full bag scan in a single pass Full 3-D bag/threat object views 3-D full image and threat object rotation
- Tunnel Opening: 1000 mm (39.4") W x 592 mm (23.3") H
- Operating Temperature: 0°C to 40 °C
- Storage Temperature: -20°C to 70 °C Relative Humidity: 10 to 90%, non-condensing

Radiation safety

All L-3 Communication Security & Detection Systems' X-ray systems comply with all international standards for radiation safety requirements and external emissions limits including the United States Code of Federal Regulations, Title 21, Section 1020.40 (21 CFR1 020.40) that apply to our products.

Washdown ready

1.1.2 Analogic ConneCT EC

Category

CT, Dual Energy Patented Computed Tomography (CT) Technology, commercial continuous throughput

Brief description

ConneCT features a new modular imaging system based on advanced medical imaging technology and an interoperable network architecture designed to maximize reliability and achieve the lowest total cost of ownership.

Brochure

Video featured on CBS, CNBC, NBC

Industry

Aviation, already been used in some airports

Company

Analogic

System specifications

Data sheet

- Throughput speed: > 600 Bags Per Hour
- Weight: 1,990 kg
- Dimensions: 2.69 m x 1.44 m x 1.75 m
- Image resolution: to be tested
- Tunnel size: 62 cm x 42 cm
- Operating Temperature: 0°C to 40 °C
- Transport / Storage Temperature: 7°C to 49°C
- Relative Humidity: - 10 – 90%, non-condensing
- Additional Cooling (Internal / External): Ambient Fan Cooled

Radiation safety

All Analogic X-ray systems are in full compliance with all international radiation safety requirements and external emission limits.

Washdown ready

1.1.3 RTT110

Category

Brief description

Industry

Company

System specifications

- Throughput speed: 0.5m/sec (good)
- Weight: 7 tonnes

- Image resolution: to be tested
- Tunnel size: 1020 x 756 mm

Radiation safety

Washdown ready

1.1.4 CTX 5800 EC

1.1.5 Category

CT, commercial continuous throughput

Brief description

CT explosives detection system

A compact explosives detection system (EDS), the CTX 5800 identifies threats in checked baggage and cargo packages.

1. Threat detection in a small footprint
2. Belt speed 0.14m/s (400-450BPH)

4. Stand-alone and in-line configurations
5. Customized networking solutions
6. High resolution 3D images from a single X-ray source

Data sheet

Industry

Aviation

Company

Smith's Detection

System specifications

- Throughput speed: up to 400-450BPH; Belt speed: 0.14m/s
- Weight: 2041kg (4,500lbs.)
- Dimensions: 1570 (W) x 1550 (H) x 2610mm (L) (59.0 x 57.8 x 102.8in)
- Image resolution: High resolution 3D images from a single X-ray source
- Tunnel opening (max. width at conveyor edge): 750 mm (29.5in)
- Conveyor height from floor: 616 mm (24")
- Operating temperature: 0° to 35°C (32 to 95°F) [up to 0° to 45°C (32 to 113°F) with air conditioning]
- Storage temperature: –7 to 49°C (20 to 120°F)
- Humidity: 10 to 95% noncondensing

Radiation safety

Meets all applicable laws and regulations with respect to X-ray emitting devices

Washdown ready

1.1.6 CTX 9800 DSi EC


Category

CT, commercial continuous throughput

Brief description

High speed CT explosives detection system

The CTX 9800 DSi explosive detection system (EDS) uses a proprietary single X-ray source, dual energy design that provides high-resolution 3D images along with 2D and 3D organic/inorganic material discrimination.

These imaging tools enhance the analysis of details and specific structures of suspected threats, allowing for efficient security decisions on all checked bags and cargo packages.

7. Customized networking solutions

9. Efficient power consumption
10. High resolution 3D images from a single X-ray source
11. Level-1 decision and Level-2 image made before bag exits the machine

Data sheet

Industry

Aviation

Company

Smith's Detection

System specifications

- Throughput speed: up to 1,800 BPH; Belt speed: 0.2, 0.3 or 0.5 m/s
- Weight: 6713 kg (14,800 lbs.)
- Dimensions: 2400 (W) × 2177 (H) × 4803 mm (L) (94.5 × 85.5 × 189.0 in.)
- Image resolution: High resolution 3D images from a single X-ray source, 3D Volumetric Rendering
- Tunnel opening (max. width at conveyor edge): 1020mm (40.2in)
- Operating temperature: 5° to 38°C (40 to 100°F)
- Storage temperature: –7 to 49°C (20 to 120°F)
- Humidity: 10 to 95% noncondensing

Radiation safety

Meets all applicable laws and regulations with respect to X-ray emitting devices

Washdown ready

Capabilities – extras

IT and AI, imaging capabilities of some kind

1.1.7 L3 ClearScan® Checkpoint CT EC

Category

CT,

Brief description

The L3 ClearScan® cabin baggage screener uses CT technology and advanced algorithms to deliver the highest level of explosives threat detection at an unprecedented false alarm rate. The aviation security system is designed to detect solid and liquid explosives, as well as HMEs, to the latest regulatory requirements without the need for any divestment. This offers the highest level of passenger convenience, allowing for liquids and electronics to be screened while remaining in cabin baggage.

- Combines dual-energy CT technology and advanced explosives detection
- High throughput/low false alarm rate
- Optional integration with automated tray return system (TRS)

Video demo, video demo 2

Industry

aviation

Company

L3Harris

System specifications

- Throughput speed: over 500 bags per hour
- Weight: 7 tonnes
- Dimensions: 6m L x 2m W x 2 m H
- Image resolution: to be tested
- Tunnel size: 1020 x 756 mm

Radiation safety

Washdown ready

1.1.8 DETECT™ 1000

Category

CT

Brief description

Based on medical computed tomography (CT) imaging technology, the DETECT™ 1000 is a powerful lens with which to see and identify smaller and more advanced threats than ever before.

The system's modern open platform design leverages High-Resolution Imaging combined with Artificial Intelligence (IA) technology to automate the threat detection and provide superior imaging to allow screeners to quickly identify prohibited items without divestiture of electronics or liquids. Soon this technology will be applied to both checked baggage and cargo.

- Artificial Intelligence and deep learning capabilities allow for optimized Automated Threat Detection
- Patent-pending "Dynamic Flow Throughput" ™ technology provides high throughput while maintaining radiation safety
- Elimination of divestiture of electronics and liquids

Industry

Aviation

Company

IDSS

System specifications

- Throughput speed:
- Weight: 3,300lbs
- Dimensions: m (L) x m (W) x 2m (H)
- Image resolution: to be tested
- Tunnel size: mm

Radiation safety

Washdown ready

1.1.9 Da Vinci Vision – part of Da Vinci Surgical Systems EC

Category

CT, 3DHD with endoscope

Brief description

Industry

Company

Intuitive | Robotic-Assisted Surgery | Da Vinci Surgical System

Radiation safety

Washdown ready

1.1.10 Equimagine – 4D true sterro-Dynamic 4D scanning

Category

CT, Stereo-Dynamic 4D scanning, robotic, digital radiography, tomosynthesis

Brief description

High accuracy, shows where bones are and a couple other things too, they also have a large CT animal scanner

Industry

Veterinary industry for scanning horses

Company

System specifications

Has 6 different types of available scans all in one. 0.03mm accuracy

Radiation safety

Unsure

Washdown ready

Not so much

1.1.11 Common Medical CT scanners

Companies

Avante

GE Healthcare

Epica Medical Innovations – Large horse scanner

Minfound,Anike,SinoVision,SternMed,NeuroLogic,Neusoft,Arineta – Medical

1.2 X-Ray

1.2.1 DRX-Revolution Mobile X-ray System EC

Category

X-ray

Brief description

A mobile X-ray system on wheels powered by a wireless DRX detector.
Ultra-manoeuvrable, automatic, collapsible column mobile imaging system.

Brochure
Video demo

Industry

Medical

Company

Carestream

System specifications

- Throughput speed: n/a
- Weight: 575 kg, (1,268 pound)
- Dimensions: [129.5-195.6] x 57.6 x 121.9 ([51-77] x 22.7 x 47.9)
- Image resolution: to be tested
- Tube arm reach of 135.1 cm; tube tilt of -10 to +90 degrees.

Radiation safety

The System is manufactured with radiation protection in accordance with IEC/EN 60601-1-3:1994.

Although exposure to high levels of X-radiation may pose a health risk, System X-ray equipment does not pose any danger when properly used. Be certain all operating personnel are properly educated concerning the hazards of radiation. Persons responsible for the System must understand the safety requirements and special warnings for X-ray operation. Review this manual and the manuals for each component in the System to become aware of all safety and operation requirements.

Washdown ready

1.2.2 X-ray Scanner CPS-X 400 EC

Category

X-ray

Brief description

The products get transferred in a continuous-flow process. Products go through the scanner where the mass allocation of each product is determined using X-ray technology. The products are then weighed on the integrated weighing station according to their individual track. The system features a two-stage safety guarding for its radiation source. The CPS-X 400 is specifically designed for weight-accurate slicing of speciality products like Swiss Cheese and those which vary in density, e.g. fat to lean ratio.

Video demo
Brochure

Food processing

Company

Weber

System specifications

- Throughput speed:
- Weight:
- Dimensions: 2,794mm (L) x 1,062mm (W) x 2,091 mm (H)
- Image resolution: to be tested

- Max. product length (mm): 2,560
- Max. product width (mm): 1,000/1,200

Radiation safety

Washdown ready

1.2.3 Multitom Rax – robotic arm x-ray

Category

Twin robotic x-ray system

Brief description

It is particularly suited for difficult exams such as trauma or orthopaedic cases. Benefit from unique insights, efficient workflows, as well as comprehensive diagnosis on a single system – and set new standards in advanced musculoskeletal and trauma imaging. Precise insights through unique automation. Efficient workflows around your patients. Comprehensive diagnosis with multiple procedures

Industry

Medical diagnosis

Company

System Specification

Ceiling mounted, multifunctional wireless footswitch, for extended anatomical coverage

These are the ways it is used

Radiation safety

Doesn’t say

Washdown ready

Probably not.

1.3 3D Cameras

1.3.1 Libra 165C EC

Category

3D imaging/scanning

Brief description

Catalogue

Video demo

Industry

Company

Nantsune Japan

System specifications

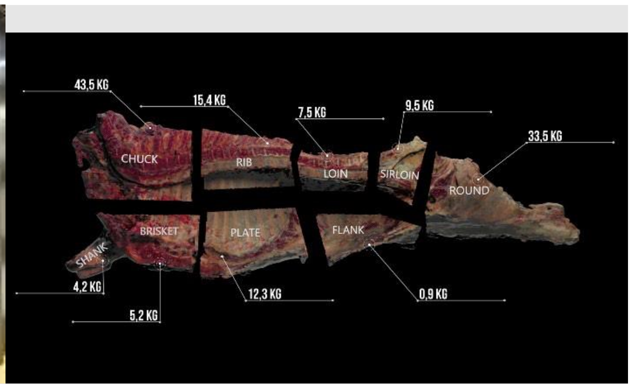
Radiation safety

Washdown ready

1.4 VR & AR

1.5 Others

1.5.1 Beef Classification Center, BCC-3™ EC



Category

Advanced multi-view stereo imaging

Brief description

Brochure
Video demo

Company

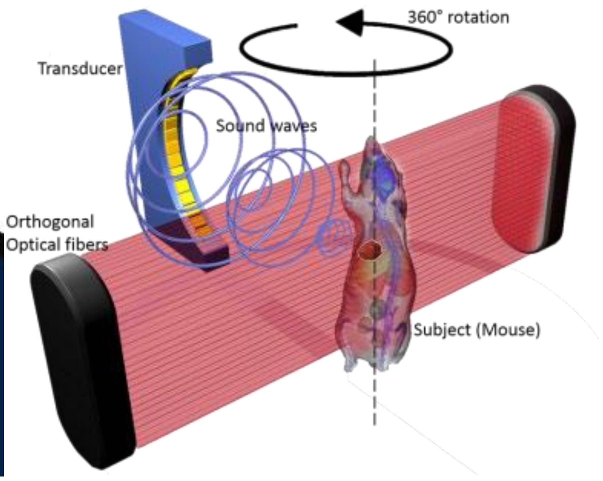
Frontmatec

System specifications

Radiation safety

Washdown ready

1.5.2 LOIS 3D Pre-clinical System EC



Category

Optoacoustic(photoacoustic) Tomography

Optoacoustic (OA) imaging is a method of acquisition and reconstruction of visual representation of biological tissue based on time-resolved detection of acoustic pressure profiles induced in tissue through absorption of optical pulses under irradiation conditions of temporal pressure confinement during optical energy deposition

Brief description

LOIS 3D combines light and sound to produce a three-dimensional image of tissue-simulating phantoms, small animals, and other types of tissue submerged in the imaging module.

LOIS-3D is the first system of its kind to produce comprehensive information based upon volumetric optoacoustic tomography depicting the absorbed optical energy (blood distribution and its oxygenation). This provides an extremely rich set of complementary anatomical and functional 3D images.

biomedical research

Company

Tomowave

System specifications

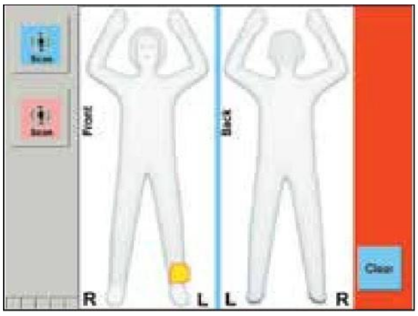
- Throughput speed:
- Weight:
- Dimensions: m L x m W x 2 m H

- Image resolution:
- Tunnel size:

Radiation safety

Washdown ready

1.5.3 ProVision® 2 EC



Concealed items are highlighted on a generic mannequin

Category

[millimetre wave (MMW) imaging technology]

The active millimetre-wave holographic imaging technology produces the image mainly by using the penetrability of MMW to clothes. The system emits millimetre waves of certain frequency to human body and the waves will penetrate clothes and be reflected back after striking human body or other hidden objects.

Brief description

The ProVision 2 is the most widely deployed advanced personnel screener in the world. It quickly screens passengers using safe millimetre wave (MMW) technology to automatically detect concealed objects made of a broad variety of concealed materials – both metallic and non-metallic.

Brochure by Leidos
Brochure by L3Harris
Video demo

Industry

Aviation, people scan

1.5.4 Company

Leidos & L3harris

System specifications

- Throughput speed: Less than six second total processing time for the scan and decision. Processes up to 200-300 people per hour depending on application.
- Weight: 698.5kg (1,540lbs)
- Dimensions: 2.27m (L) x 1.5m (W) x 2.36 m (H)
- Image resolution:
- Tunnel size:
- Operating temperature: 0° to 35°C (32 to 95°F)
- Humidity: 10-90% non-condensing

Radiation safety

The ProVision 2 does not use X-rays or ionizing radiation.